Synchronization and Pattern Formation in Coupled Nonlinear Optical Systems

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Introduction

h Introduction

- Analyse coupled nonlinear optical systems
- Possible information transfer device
- Interaction of coupled solitary (localized) structures





Coupled Nonlinear Optical Systems with Pattern Formation

Defining the System



- Two pattern forming single feedback mirror systems
- Unidirectional coupling from system 1 to system 2
- Separation of refraction and diffraction

[Scroggie, Firth, PRA 53,2752 (1996)] [Mitschke et al., PRA 33,3219 (1986)]

Defining the System



- Interesting points
 - Synchronization of patterns (regular and chaotic)
 - Transmission of patterns
 - Solitary structures

[Scroggie, Firth, PRA 53,2752 (1996)] [Mitschke et al., PRA 33,3219 (1986)]

Theoretical Analysis - The Generalized Bloch Type Equation

• Generalized Bloch type equation for $\boldsymbol{m} = (u, v, w)$

(1) $\dot{\boldsymbol{m}} = \boldsymbol{\Omega} imes \boldsymbol{m} - \gamma_{\mathrm{eff}} \boldsymbol{m} + \boldsymbol{P}$

- $\mathbf{\Omega} = (\Omega_x, \Omega_y, \Omega_z)$: magnetic field
- $\gamma_{
 m eff}$: effective relaxation rate
- P: pumprate due to the injected electrical field (i.e. the laser)
- No magnetic field
- Equations uncouple
- Quasiskalar description

(2)
$$\dot{w} = -(\gamma - \text{Diff}\nabla_{\perp}^2)w + P_+(1-w) - P_-(1+w)$$

- w : magnetization of the medium
- P_±: pumprate of the positive / negative circular polarized light
 [Mitschke et al., PRA 33,3219 (1986)] [Scroggie, Firth, PRA 53,2752 (1996)]

Theoretical Analysis - Where Are The Patterns?



b Synchronization / Correlation

Synchronization

- Transfer fields $\phi_i \in I\!\!R(n imes n)$ to vectors $\phi_i \in I\!\!R(n st n)$
- substract mean values, to only calculate the synchronization of the variying fields

(3)
$$oldsymbol{u}_i=oldsymbol{\phi}_i-.$$

The function to derive the synchronization rates is choosen to

(4)
$$SyncRate(\boldsymbol{u},\boldsymbol{v}) = \frac{1}{||\boldsymbol{u}||||\boldsymbol{v}||} \boldsymbol{u}.\boldsymbol{v}$$

Local Correlation

- Time series of one pixel $\phi_i(\boldsymbol{r},t) \forall \boldsymbol{r}$
- substract mean values (Correlation coefficient from Pearson)
- take last N timesteps $\rightarrow u(\mathbf{r}) = (\phi_i(\mathbf{r}, t_n))_{n=1..N}$

(5)
$$LocCorr(u,v)(\boldsymbol{r}) = \frac{1}{||u||||v||}u.v$$



Numerical Results – One Cell $\lambda/8$ -Case

Numerical Results - Solitary Structures Region

• $\lambda/8$ -Setting, Bistabel system, Pitchfork-bifurcation



Homogenous state of the system (a) $\alpha = 0^{\circ}$, (b) $\alpha = 10^{\circ}$. Results of the linear stability Analysis (c) $\alpha = 0^{\circ}$, (d) $\alpha = 10^{\circ}$ (— positive branch, - - negative branch).

Numerical Results - Solitary Structures Region



(a) Grey shaded is the region where solitary structures exist. (b) Solitary object in a patterned undergound $(I_{0I} = 400 \text{mW})$. (c),(d) Cut through, real image of a solitary object on a homogenous underground $(I_{0I} = 300 \text{mW})$. The parameters are $\gamma = 200$ /s, $D = 250 \text{mm}^2/\text{s}$, $\alpha_0 = 2.2168$, $1/(2k_0) = 0.468 \text{mm}$, L = 15 mm, d = 0.88 dm, $\alpha_I = 10^\circ$, $\alpha_{II} = -10^\circ$, $\varphi_I = \varphi_{II} = \pi/4$, $R_I = R_{II} = 0.99$, s = 0.0, $\overline{\Delta} = 6.0$.

Numerical Results - Different Solitary Structures



- Different solitary structures stable
- Discrete Family of solitary structures



LS 3

LS 4

[Pesch et al., PRL 95,143906(2005)]

Numerical Results - Labyrinths





(right) Regions of existance for labyrinths and localized patterns.

(left) Hexagon, localized pattern (positive and negative Hexagon) and labyrinthine structures.

Parameters : like solitary structures, except $\alpha_I = 0^o$

[Diss. Schüttler, 2006]



Numerical Results – Coupling solitons

Numerical Results - Solitary Structures on Random State



(a) Synchronisation rate against increasing coupling with $\lambda/8$ -plate in both systems, initial condition is a pos. solitary object in system 1 and a random state in system 2. Intensities $I_{0I} = 300$ mW, Angles : $\alpha_I = \alpha_{II} = 10^{\circ}$. Lines drawn to guide the eye. (b)(i) Weak coupling leads to neg. hexagonal structures with weak imprint of sol. obj. in cell *II*. (ii) Medium coupling leads to imprint of sol. obj. in cell *II* on negative background. (iii) Initial positive solitary object of cell *I* and transmitted sol. obj. for very strong coupling $(I_{0II} = 300$ mW).

Numerical Results - Transmission of Solitary Objects



(a) Synchronisation rate against increasing coupling with $\lambda/8$ -plate in both systems, initial condition is a pos. solitary object in system 1 and a homogenous state in system 2. Intensities $I_{0I} = 300$ mW, Angles : $\alpha_I = \alpha_{II} = 10^{\circ}$. Lines drawn to guide the eye. (b)(i) Initial positive solitary object of cell *I* and transmitted sol. obj. for very strong coupling ($I_{0II} = 300$ mW) or medium coupling ($I_{0II} = I_{II eff}$). (ii) Weak coupling leads to weak imprint of sol. obj. in cell *II*. (iii) Medium coupling leads to formation of hexagonal structures with weak imprint of sol. obj.. (iv) Strong coupling leads to hexagonal structures with transmitted sol. obj..

Numerical Results - Transmission of Solitary Objects



(a) Color coded 2D-plot of cell II with s = 0.90, (b) inverted corresponding 3D-plot (for better visability). (c) Color coded 2D-plot of cell II with s = 1.00, (d) inverted corresponding 3D-plot.

Numerical Results - Pos. Sol. Obj. on Neg. Sol. Obj.



(a) Synchronisation rate with increasing coupling with $\lambda/8$ -plate in both systems, initial condition is a pos. solitary object in system 1 and a negative one in system 2. Intensities $I_{0I} = I_{0II} = 300$ mW, Angles : $\alpha_I = -\alpha_{II} = 10^{\circ}$. Lines drawn to guide the eye. (b) (i) Initial negative solitary object of cell 2, (ii) "kicked" solitary

objects with coupling strength s = 0.03, (iii) final field with s = 0.90 and (iv) final field with s = 1.00.

Numerical Results - Coupling identical solitons s = 0.02



1D-Cuts of stable distances along the connection line (green = Cell I, blue = Cell II)

Numerical Results - Coupling inverse solitons s = 0.03



Numerical Results - Different Solitons - Mechanisms

- Coupling of solitons yields three basic mechanisms :
 - Destroying Soliton in the second cell is destroyed.

Resulting pattern :

- homogenous state
- generic hexagon
- Moving Soliton in the second cell is moved.

Resulting pattern :

- shape of soliton in the second cell unchanged, position changed
- shape of soliton in the second cell slightly changed, position changed
- Morphing Soliton in the second cell is morphed.

Resulting pattern :

soliton in the second cell synchronizes with first soliton

Numerical Results - Different Solitons - Destroying

- solitons of different sizes
- solitons with different direction



Coupling of different solitons with different direction. (left) LS4 positive - LS2 negative, (right) LS2 positive - LS4 negative.

Parameters : $\overline{\Delta} = 6.0$, $\alpha_I = -\alpha_{II} = 5^{\circ}$, $I_I = I_{II} = 300$ mW. (green = Cell I, blue = Cell II)

Numerical Results - Different Solitons - Moving

• LS1 \pm - LS1 \pm



(left) Stable distances and max synchronization with initial solitons in the second cell. (right) 1D-Cuts at the connection line (stable distance, max deformation). Parameters : $\overline{\Delta} = 6.0$, $\alpha_I = -\alpha_{II} = 5^{\circ}$, $I_I = I_{II} = 300$ mW. (green = Cell I, blue = Cell II)

Numerical Results - Different Solitons - Moving

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Numerical Results - Different Solitons - Morphing

- different solitons
- same direction



Morphing of solitons. (left) LS2 pos. - LS3 pos. s = 0.010, (right) LS2 pos. - LS4 pos. s = 0.030. Parameters : $\overline{\Delta} = 6.0, \alpha_I = -\alpha_{II} = 5^o, I_I = I_{II} = 300$ mW. (green = Cell I, blue = Cell II)

Numerical Results - Different Solitons - Morphing

- different solitons
- same direction



Morphing of solitons. (left) LS3 pos. - LS2 pos. s = 0.035 and (right) LS4 pos. - LS3 pos. s = 0.045. Parameters : $\overline{\Delta} = 6.0, \alpha_I = -\alpha_{II} = 5^o, I_I = I_{II} = 300$ mW. (green = Cell I, blue = Cell II)



Numerical Results – Labyrinth coupling

Numerical Results - Labyrinth coupling





Numerical Results – Domains $\lambda/4.\lambda/8$

Numerical Results - Domains

L4.L8 case





(left) Region of existance of domain structures (right) Developing of domains with increasing coupling (top left) 8f(II) + 8f(I), s = 2.2, (top right) domains and fronts D, s = 2.5 (bottom left) labyrinthine structure s = 3.0. (Parameter : $\overline{\Delta} = 6.0$, $I_{0I} = 300$ mW and $I_{0II} = 290$ mW). (bottom right) pure circular domains (Parameter : $\overline{\Delta} = 5.5$, $I_{0I} = 355$ mW und $I_{0II} = 345$ mW).



Conclusions / Outro

Conclusions / Outro

- Coupled two transverse pattern forming nonlinear optical devices
- Transmission of solitary objects
- Interaction of pos. and neg. solitary objects
- Moving of solitary objects
- Destroying of solitary objects
- Morphing of solitary objects
- Coupling of labyrinthine structurse Synchronisation
- Coupling of two different regluar patterns yields domain structures

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Thank you for listening!

Theoretical Analysis - The Pumprates final



Matrixoperator for the medium given by

(6)
$$P_M(x,w) = \begin{pmatrix} \mathcal{P}_{+,M}(x,w) & 0 \\ 0 & \mathcal{P}_{-,M}(x,w) \end{pmatrix}$$

 Combining the operators easily gives the pumprates at certain points

$$P_{\pm} \sim |\mathcal{E}_{\pm,f}(0,t)|^2 + |\mathcal{E}_{\pm,b}(0,t)|^2$$

(7) ~
$$|\mathcal{E}^{0}_{\pm}|^{2} + R|M(\phi, \alpha)\mathcal{P}_{FP}(2d)P_{M}(L, w)\mathcal{E}^{0}_{\pm}|^{2}$$

[Grosse-Westhoff et al., J.Opt.B. 2,386 (2000)



System 1

Theoretical Analysis - Inserting the Coupling

 Uncoupled systems gives two differential equations

$$\dot{w}_{I,II} = -(\gamma - \operatorname{Diff} \nabla_{\perp}^{2}) w_{I,II}$$

$$+P_{+I,II}(1 - w_{I,II}) - P_{-I,II}(1 + w_{I,II})$$
(8) = NL_{I,II}(w_{I,II})
$$\overset{\mathsf{Laser 1}}{\longrightarrow}$$

$$\overset{\mathsf{Laser 1}}{\longrightarrow}$$

coupling strength k

Input in cell two is

(9) $\mathcal{E}^{0}_{\pm,II} + \mathcal{E}_{\pm,I,b}(L,t)$

- Signal trans. NL NL2 Polarisator 1 Mirror 1 Cell 1 Laser 2 Cell 2 Polarisator 2 Mirror 2 System 1 System 2
- Neglegting interference terms $\mathcal{E}^{0*}_{\pm,II}\mathcal{E}_{\pm,I,b}(L,t) \rightarrow 0, \mathcal{E}^{0}_{\pm,II}\mathcal{E}_{\pm,I,b}(L,t)^* \rightarrow 0$

Theoretical Analysis - Inserting the Coupling

- Coupled System gives rise to differential eq. system
- (10) $\dot{w}_I = \operatorname{NL}_I(w_I)$

(11)
$$\dot{w}_{II}$$
 = NL_{II} $(w_{II}) + k$ NL_{III} (w_I, w_{II})

- $NL_{II}(w_{II})$: Terms due to laser 2
- $\mathrm{NL}_{III}(w_I, w_{II})$: Terms due to the coupling
- "Coupling" nonlinearity is

 $\operatorname{NL}_{III}(w_I, w_{II}) \sim |\mathcal{E}_{\pm,I,b}(L,t)|^2$

 $+R|M(\phi_{II},\alpha_{II})\mathcal{P}_{FP}(2d)P_M(L,w_{II})\mathcal{E}_{\pm,I,b}(L,t)|^2$

