

Filaments

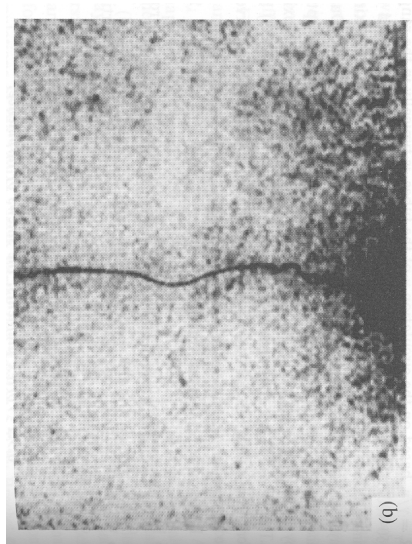
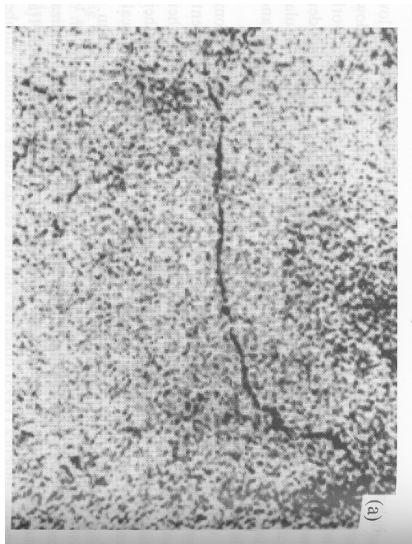
Michael Köpf

29. August 2007

Motivation: Experimental Evidence



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Motivation: Experimental Evidence

- Now that we know that filaments are there, what role do they play in turbulence? („Filaments - Dog or Tail?“)
- A good starting point might be to learn about vortex filaments in general.

① Dynamics of an Isolated Filament

- Basic Definitions
- A Special Case: Smoke Ring Dynamics
- Localized Induction Approximation (LIA)
- Beyond LIA: Global Induction

② Application to Vortex Knots

- Knots, Torus Knots
- Numerical Results

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Basic Equations

- Euler equation of an incompressible fluid

$$\partial_t \vec{u} + \vec{u} \cdot \nabla \vec{u} = -\nabla p \quad \nabla \cdot \vec{u} = 0$$

- Evolution of vorticity

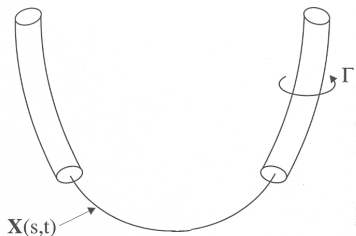
$$\partial_t \vec{\omega} + \vec{u} \cdot \nabla \vec{\omega} = \vec{\omega} \cdot \nabla \vec{u} \quad \text{with vorticity } \vec{\omega} = \nabla \times \vec{u}$$

- Vortex-stretching due to the term $\vec{\omega} \cdot \nabla \vec{u}$ vanishes in two dimensions.

Filaments

Definition

A *filament* is an isolated vortex tube of small diameter dA and constant vorticity ω .



- Let $\vec{X}(s, t)$ be the centerline of a filament and s a parameter of arc length.
- This is conveniently described by means the Serret-Frenet equations from differential geometry.

Filaments

Serret-Frenet Equations

$$\vec{X}' = \vec{t}$$

$$\vec{t}' = \kappa \vec{n}$$

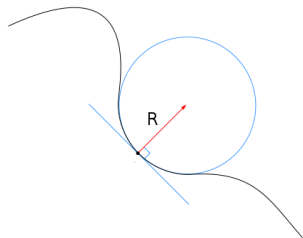
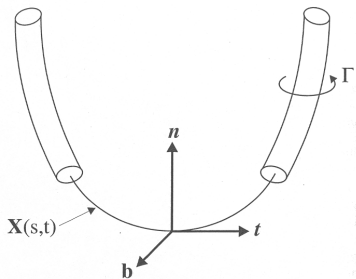
$$\vec{n}' = \tau \vec{b} - \kappa \vec{t}$$

$$\vec{b}' = -\tau \vec{n}$$

$$' \equiv \frac{\partial}{\partial s}$$

$$\text{Curvature } \kappa = \frac{\|\vec{t}'\|}{\|\vec{t}\|}, \quad \kappa = \frac{1}{R}$$

$$\text{Torsion } \tau = \frac{\vec{b} \cdot \vec{n}'}{\|\vec{X}'\|} = \frac{\vec{X}' \times \vec{X}'' \cdot \vec{X}'''}{\|\vec{X}' \times \vec{X}''\|^2}$$



Dynamics of a Single Filament

- Formal analogue to magnetostatics:

$$\begin{aligned}\nabla \cdot \vec{u} &= 0 & \nabla \cdot \vec{B} &= 0 \\ \nabla \times \vec{u} &= \vec{\omega} & \nabla \times \vec{B} &= \mu_0 \vec{j}\end{aligned}$$

- Biot-Savart Law:

$$\vec{u}(\vec{x}) = -\frac{1}{4\pi} \int d^3x' \frac{(\vec{x} - \vec{x}') \times \vec{\omega}(\vec{x}')}{\|\vec{x} - \vec{x}'\|^3}$$

- Consider ideal filaments

$$\vec{\omega}(\vec{x}) = \Gamma \int ds' \delta(\vec{x} - \vec{X}(s')) \vec{t}$$

⇒ This is analogous to the concept of filamentary wires

Dynamics of a Single Filament

- Theorem of Biot-Savart for an ideal filament:

$$\vec{u}(\vec{x}) = -\frac{\Gamma}{4\pi} \int_{\vec{X}} ds' \frac{[\vec{x} - \vec{X}(s')] \times \vec{t}}{\|\vec{x} - \vec{X}(s')\|^3}$$

- Artifact of the idealization: $\vec{u}(\vec{x})$ diverges like $\frac{1}{\|\vec{x} - \vec{X}\|}$
- Self-induction:

$$\vec{u}(\vec{X}(s)) = -\frac{\Gamma}{4\pi} \int_{\vec{X}} ds' \frac{[\vec{X}(s) - \vec{X}(s')] \times \vec{t}}{\|\vec{X}(s) - \vec{X}(s')\|^3}$$

Taylor-Expansion yields

$$\vec{u}(\vec{X}(s)) = \frac{\Gamma}{4\pi} \left[\vec{X}' \times \vec{X}'' \int \frac{ds'}{|s - s'|} + \mathcal{O}(1) \right]$$

Dynamics of a Single Filament

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A Special Case: Smoke Ring Dynamics

- Assume constant vorticity inside the ring:

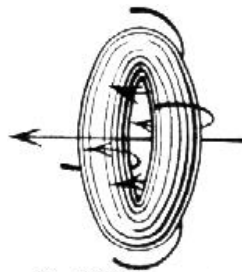
$$\omega_0(\vec{x}) = \begin{cases} \frac{\Gamma}{\pi\sigma^2}, & |\vec{x}| < \sigma \\ 0, & |\vec{x}| > \sigma. \end{cases}$$

- Lamb (1932): Ring moves perpendicular to its plane at velocity

$$u_{\perp} = \frac{\Gamma}{4\pi R} \left[\ln \left(\frac{8R}{\sigma} \right) - \frac{1}{4} + \mathcal{O} \left(\frac{\sigma}{R} \right) \right]$$

With $R/\sigma \gg 1$:

$$\begin{aligned} \ln \left(\frac{8R}{\sigma} \right) &\approx \text{const.} \\ \Rightarrow u_{\perp} &= \frac{C_1}{R} \sim \kappa. \end{aligned}$$



Local Induction Approximation (LIA)

- To render the self-induction integral finite, introduce a cut-off so that $|s' - s| > \epsilon$
- Further, self-induction by distant parts of the filament are neglected by limiting the Taylor-expansion to the leading order.

$$\frac{\partial \vec{X}(s, t)}{\partial t} = \ln \left(\frac{L}{\epsilon} \right) \frac{\Gamma}{4\pi} \left(\vec{X}'(s, t) \times \vec{X}''(s, t) \right)$$

- Rescaling t yields the local induction evolution (LIE)

$$\Rightarrow \frac{\partial \vec{X}}{\partial t} = \kappa(s, t) \vec{b}(s, t).$$

→ Around s the filament looks like a ring-vortex of radius $1/\kappa(s, t)$, the local curvature radius of the filament.

- This approximation is known as *Local Induction Approximation* (LIA), sometimes also called „Smoke Ring Approximation“

Hasimoto-Transformation

- Starting from the LIA evolution equation $\dot{\vec{X}}(s, t) = \kappa(s, t)\vec{b}$, introduce the following formal substitutions

$$\vec{N}(s, t) = (\vec{n} + i\vec{b}) e^{i\Phi} \text{ mit } \Phi = \int_0^s ds \tau(s, t)$$

$$\psi(s, t) = \kappa(s, t) e^{i\Phi}$$

$$\kappa = |\psi| \quad \tau = \Phi'$$

$$\Rightarrow -i\dot{\psi} = \psi'' + \frac{1}{2}|\psi|^2\psi.$$

- Time evolution in LIA can be related to a cubic Schrödinger equation.

Soliton Solutions to the LIA Equation

- Like the non-linear SE the LIA has soliton solutions
- Consider the simplest case: a wave travels along the filament at constant speed c

$$\psi(s - ct) = \kappa(s - ct)e^{i \int_0^s ds \tau(s-ct)}.$$

Into the NLSE

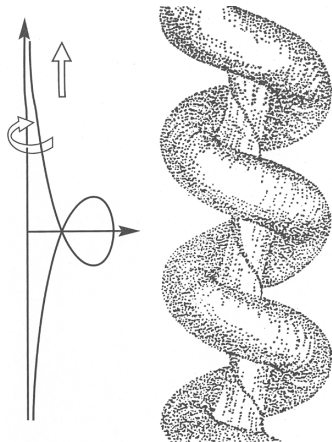
$$\Rightarrow (c - 2\tau)\kappa^2 = 0 \quad \tau = \tau_0 = \frac{c}{2} = \text{const.}$$

- Integration yields

$$\kappa = \pm 2\tau_0 \operatorname{sech}(\pm \tau_0(s - ct)).$$

Soliton Solutions to the LIA Equation

- κ and τ together with the Serret-Frenet equations yield parametric expressions of $(\vec{X}, \vec{t}, \vec{n}, \vec{b})$.



LIA: Properties & Shortcomings

Assumptions:

- Filaments have to be sufficiently thin ($\sigma/R \ll 1$)
- Induction by distant parts of the filament have to be neglectable

Consequences:

- Calculations are drastically simplified (especially useful for numerical simulations)
- There are several conserved quantities:
 - Maximum projected area of a closed vortex filament \mathcal{C}

$$\vec{P}(t) = \frac{1}{2} \int_{\mathcal{C}} ds (\vec{X} \times \vec{X}')$$

(Momentum conservation) \Rightarrow A non-circular vortex ring can never become perfectly circular

- Total torsion
- Arc length \Rightarrow No vortex-stretching!
- ...

Beyond LIA: Global Induction Effects

General case: „Full“ Biot-Savart law

- Remove the divergent part of the Biot-Savart integral

$$\vec{u}(X(\vec{s}, t)) = -\frac{\Gamma}{4\pi} \int_{\vec{X}} ds' \frac{[\vec{X}(s, t) - \vec{X}(s', t)] \times \vec{t}}{\|\vec{X}(s, t) - \vec{X}(s', t)\|^3}$$

by cutting off the line integral (just as in LIA).

- Take higher orders of the Taylor expansion into account
- Influences on the filament evolution can thus be divided in two portions:
 - local influences: LIA
 - global influences: Higher order terms

① Dynamics of an Isolated Filament

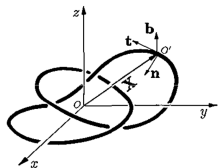
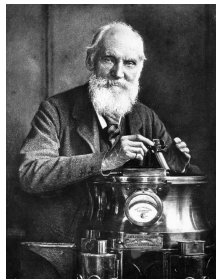
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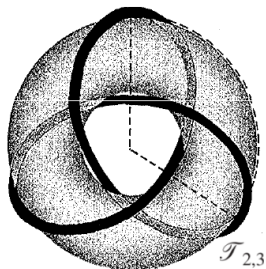
Vortex Knots

- A *knot* is a circle embedded in \mathbb{R}^3
- Lord Kelvin (1875) was the first to investigate the existence and stability of vortex knots in Euler flow.



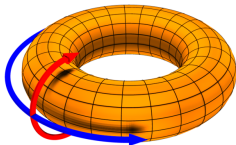
- Knots are useful for modelling of (topologically) complex structures.

Torus Knots

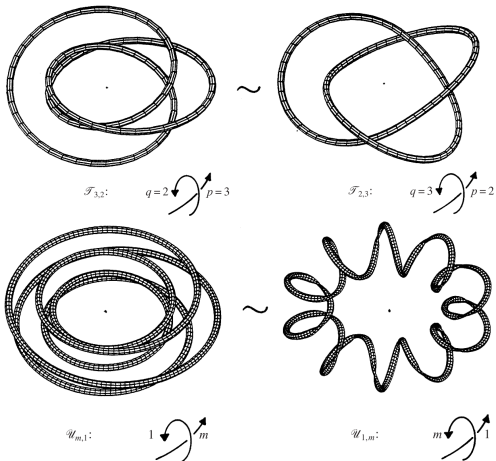


- Closed curves which can be drawn on a torus' surface

- Classification by number of toroidal (p) and poloidal (q) windings: $\mathcal{T}_{p,q}$



Torus Knots



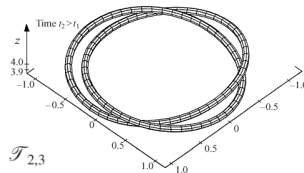
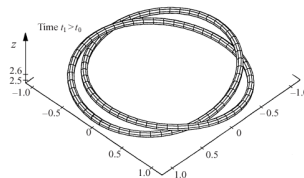
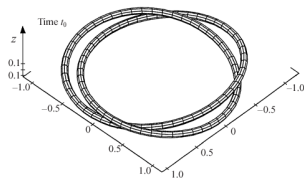
Dynamics of Vortex Knots

Evolution in LIA

Theorem (Ricca 1995)

A torus knots $\mathcal{T}_{p,q}$ is linearly stable in LIA, if and only if $p < q$.

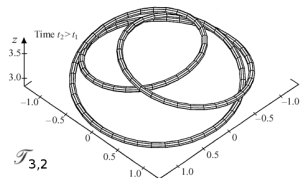
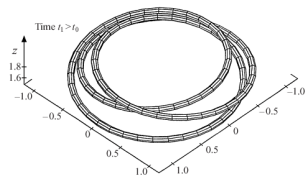
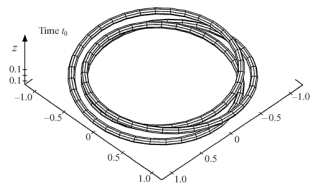
- Numerical simulations (Ricca, Samuels, Barenghi 1997) indicate, that vortex knots which satisfy this condition can travel distances several times their own size.



Dynamics of Vortex Knots

Evolution in LIA

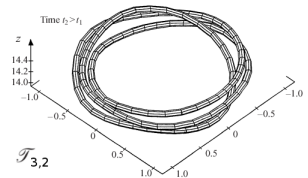
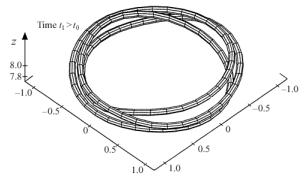
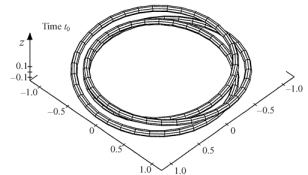
- In the reverse case, $q > p$, the vortex knot structure decays much faster.



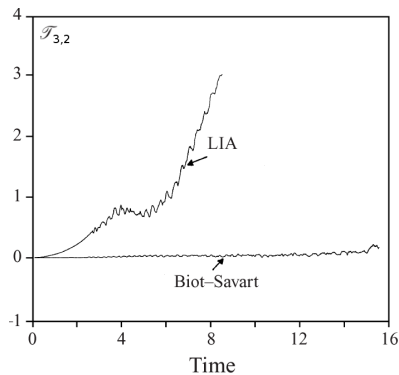
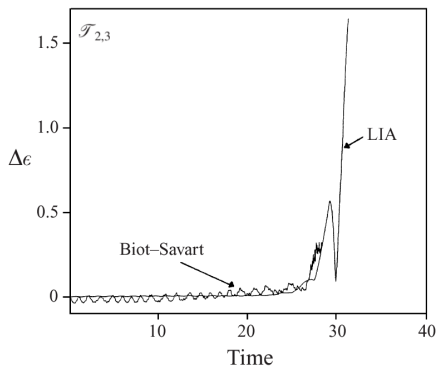
Dynamics of Vortex Knots

Development due to the „full“ BSL

- Adding global influences stabilizes the knot evolution in both cases.
- This is due to a rotation of the „arms“ of the knot around each other (see Jiminez (1975) on stability of co-rotating vortices),



LIA vs. Full Biot-Savart Law



$$\epsilon = \frac{R_{\max} - R_{\min}}{2}$$

Summary

- In order to understand the role they play in turbulence filaments are investigated
- The dynamics of an isolated vortex filament in Euler flow is described by the Biot-Savart law \rightarrow Divergence has to be handled
- From the LIA viewpoint, the filament is locally seen as part of a vortex ring of a radius corresponding to local curvature
- By Hasimoto transformation the LIA evolution equation can be related to a NLSE \rightarrow Solitons
- The LIA is the local portion of the desingularized BS integral
- Knot vortex dynamics gain stability by taking into account the global portions of the BSI.