



# Localized structures in reaction-diffusion systems

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# Outline

## 1 Introduction

- Reaction-Diffusion Systems
- Experimental system in question
- Possible Model Systems

## 2 Localized structures in 3KRD system

- Phenomenological 3KRD model
- Stationary Turing structures
- Localized structures and their stability





# Reaction-Diffusion Systems

$$\partial_t \mathbf{u} = \mathbf{D} \nabla^2 \mathbf{u} + \mathbf{R}(\mathbf{u})$$

- $\mathbf{u} = \mathbf{u}(\mathbf{r}, \mathbf{t}) = (u_1, u_2, \dots, u_n)^T$  – a vector of concentration variables,  $\mathbf{r} \in \mathbb{R}^m$ ,  $m = 1, 2, 3$ ;
- $\nabla^2$  – the Laplace operator;
- $\mathbf{R}(\cdot)$  – a local reaction kinetics;
- $\mathbf{D}$  – a diagonal diffusion coefficient matrix;



## Reaction-Diffusion Systems: 1K systems

1937:

- **R. Fisher** *The wave of advance of advantageous genes;*
- **A. N. Kolmogorov, I. G. Petrovsky, N. Piskunoff** *A study of the equation of dissusion with increase in the quantity of matter, and its application to a bilological problem;*



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$$\partial_t u = d^2 u_{xx} + u(1 - u)(u - \alpha), \alpha \in (0, 1)$$



# Reaction-Diffusion Systems: 2K systems

1952:

- **A. M. Turing** *The chemical basis of morphogenesis*

$$\partial_t u = D_u \nabla^2 u + f(u, v),$$

$$\partial_t v = D_v \nabla^2 v + g(u, v)$$







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Belousov-Zhabotinsky reaction, other autocatalytic and oscillatory chemical reactions, different patterns on animal's skin, nerve pulse transmission, bacteria growth processes, structures, observed in semiconductors or gas-discharge systems, .....



## Reaction-Diffusion Systems: 3K and more

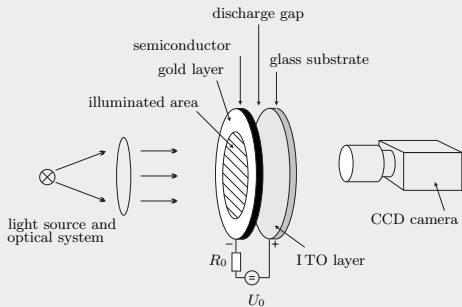
$$\partial_t u_\alpha = D_\alpha \nabla^2 u_\alpha + R_\alpha(u)$$

a model of blood clotting, population dynamics, ecology, photosensitive Belousov-Zhabotinsky reaction, glycolysis, a model of CO oxidation on Pt(110), a model of Dictyostelium amoebae, patterns arising in gas-discharge system.....



## Experimental set-up

Planar dc gas-discharge system with high-ohmic electrode:

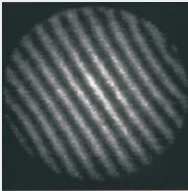


- $d = 0.1 - 2 \text{ mm}$ ;
- Gases:  $\text{N}_2, \text{He}, \text{Ar}$ ;
- $p \approx 30 - 400 \text{ hPa}$ ;
- Semiconductor: GaAs
- $d_c = 0.5 - 1.5 \text{ mm}$ ;
- $\rho_{\text{SC}} \approx 10^7 - 10^8 \Omega \cdot \text{cm}$ ;
- $U_0 = 1 - 5 \text{ kV}$

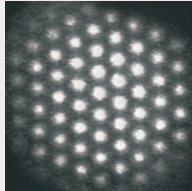


# Examples of observed patterns

stripes



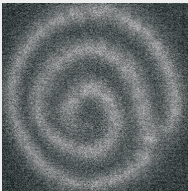
hexagons



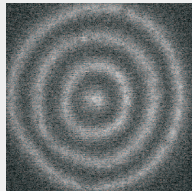
spots



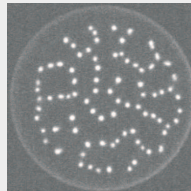
spirals



targets



chains





# Possible Model Systems

The current patterns are 3D objects, evolving on the time scale of 1 ms – 1 s





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- fluid based models, (e.g., drift-diffusion):  $\tau_e \approx 10$  ns;
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an appropriate reduced discharge models should be developed or qualitative models should be used





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## Phenomenological three-component RD model

$$\partial_t u = D_u \Delta u + f(u) - \kappa_3 v + \kappa_1 - \frac{\kappa_2}{\|\Omega\|} \int_{\Omega} u dr,$$

$$\tau \partial_t v = D_v \Delta v + u - v;$$

$u = u(\mathbf{r}, t)$ —is related to the avalanche multiplication of charged carriers in the discharge gap;

$v = v(\mathbf{r}, t)$ —the voltage drop at the semiconductor plate;

$\kappa_1$ — is connected with the normalized applied voltage;

$\kappa_2$ — describes a normalized internal resistance of the voltage source.



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## Phenomenological three-component RD model

$$\begin{aligned}\partial_t u &= D_u \Delta u + f(u) - \kappa_3 v - \kappa_4 w + \kappa_1, \\ \tau \partial_t v &= D_v \Delta v + u - v, \\ \theta \partial_t w &= D_w \Delta w + u - w;\end{aligned}$$

$$\begin{aligned}u &= u(\mathbf{r}, t), v = v(\mathbf{r}, t), w = w(\mathbf{r}, t), \mathbf{r} \in \mathbb{R}^2, f(u) = \lambda u - u^3, \\ D_u, D_v, D_w, \lambda, \tau, \theta, \kappa_3, \kappa_4 &\geq 0\end{aligned}$$





## Turing instability

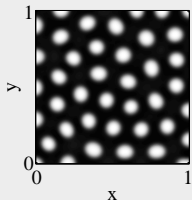
The idea (Turing, 1952):

- The homogeneous solution of the system is stable in absence of diffusion;
- A difference in diffusion constants of components could be enough to destabilize the homogeneous solution;
- Another control parameter can be used (in our case we choose  $\kappa_1$  as the control parameter)

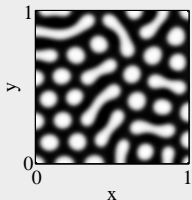


# Stationary Turing patterns

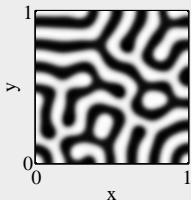
(a)  $\kappa_1 = -1.1$



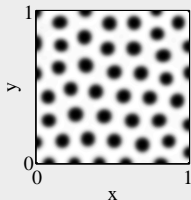
(b)  $\kappa_1 = -0.5$



(c)  $\kappa_1 = 0.0$



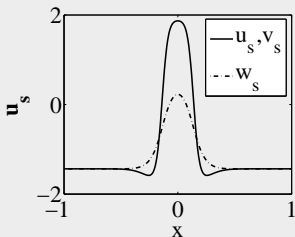
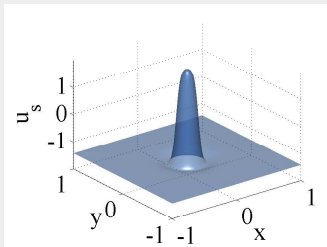
(d)  $\kappa_1 = 1.1$



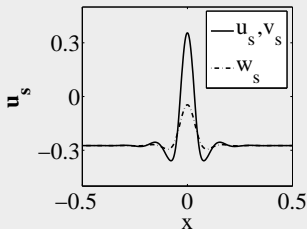
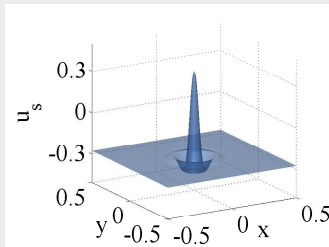


## Stationary solutions

(a)



(b)



# Linear stability analysis

- The system in general form:  $\partial_t \mathbf{u} = \mathfrak{L} \mathbf{u}$ ;



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- Equation for perturbation  $\tilde{\mathbf{u}} = \mathbf{u} - \mathbf{u}_s$ :

$$\partial_t \tilde{\mathbf{u}} = \mathcal{L}'(\mathbf{u}_s)\tilde{\mathbf{u}} + \frac{1}{2!}\mathcal{L}''(\mathbf{u}_s)\tilde{\mathbf{u}}\tilde{\mathbf{u}} + \frac{1}{3!}\mathcal{L}'''(\mathbf{u}_s)\tilde{\mathbf{u}}\tilde{\mathbf{u}}\tilde{\mathbf{u}} + \dots,$$

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- Eigenvalue problem:  $\mathcal{L}'(\mathbf{u}_s)\mathcal{F} = \lambda\mathcal{F}$ ;

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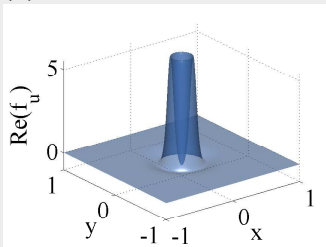
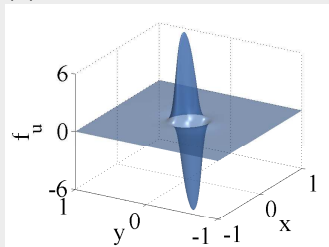
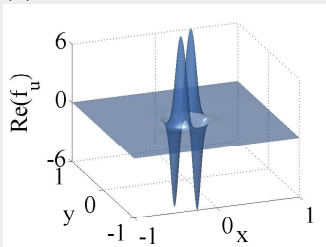
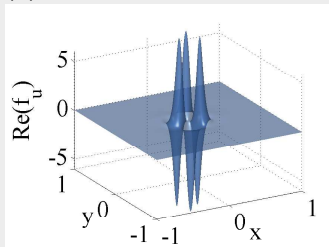
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- $\tilde{\mathbf{u}} \sim \tilde{\mathbf{u}}_n e^{in\phi}$ :

$$\lambda_n \tilde{\mathbf{u}}_n = \mathcal{L}'_p \tilde{\mathbf{u}}_n,$$

## Critical modes

(a)  $n = 0$ (b)  $n = 1$ (c)  $n = 2$ (d)  $n = 3$ 



## Properties of the operator $\mathcal{L}'(\mathbf{u}_s)$

$$\mathcal{L}'(\mathbf{u}_s) = \begin{pmatrix} D_u \Delta + \lambda - 3\bar{u}^2 & -\kappa_3 & -\kappa_4 \\ \frac{1}{\tau} & \frac{D_v \Delta - 1}{\tau} & 0 \\ \frac{1}{\theta} & 0 & \frac{D_w \Delta - 1}{\theta} \end{pmatrix}$$

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$$\mathcal{L}'(\mathbf{u}_s) = ML(\mathbf{u}_s),$$

where

$$M = M^\dagger = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1/\kappa_3\tau & 0 \\ 0 & 0 & -1/\kappa_4\theta \end{pmatrix},$$

and

$$L = L^\dagger = \begin{pmatrix} D_u \Delta + \lambda - 3u_s^2 & -\kappa_3 & -\kappa_4 \\ -\kappa_3 & -\kappa_3 D_v \Delta + \kappa_3 & 0 \\ -\kappa_4 & 0 & -\kappa_4 D_w \Delta + \kappa_4 \end{pmatrix}.$$



## Properties of the operator $\mathcal{L}'(\mathbf{u}_s)$

- Two eigenvalue problems:

$$\mathcal{L}'(\mathbf{u}_s)\mathcal{F} = \lambda\mathcal{F}, \quad \mathcal{L}'^\dagger(\mathbf{u}_s)\mathcal{F}^* = \bar{\lambda}\mathcal{F}^*,$$

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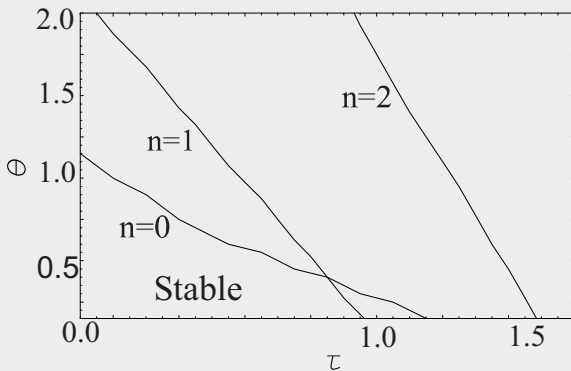
- If  $\lambda$  is real (e.g.,  $\lambda = 0$ ):

$$\mathcal{G}_r^* = M^{-1}\mathcal{G} = \begin{pmatrix} \frac{\partial \mathbf{u}_s}{\partial \mathbf{r}} \\ -\kappa_3 \tau \frac{\partial \mathbf{v}_s}{\partial \mathbf{r}} \\ -\kappa_4 \theta \frac{\partial \mathbf{w}_s}{\partial \mathbf{r}} \end{pmatrix}.$$

However, in this case  $\langle \mathcal{G}_r^* | \mathcal{G} \rangle \neq 0$ .



# Stability diagramm





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- In the limit case the operator  $\mathcal{L}'(\mathbf{u}_s)$  is Hermitian. All  $\lambda$ 's are real.



## Order of bifurcations

- Let us now consider  $\tau > 0$ :

$$\mu f_u = D_u \Delta f_u + (f'(u_s) - \kappa_3) f_u - \kappa_4 f_w$$

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$$\left(\mu - \frac{\kappa_3 \tau \mu}{\tau \mu + 1}\right) f_u = D_u \Delta f_u + (f'(u_s) - \kappa_3) f_u - \kappa_4 f_w$$

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$$\mu_{1,2} = \frac{\lambda \tau - 1 + \kappa_3 \tau}{2\tau} \pm \sqrt{\frac{\lambda}{\tau} + \left(\frac{\lambda \tau - 1 + \kappa_3 \tau}{2\tau}\right)^2}$$

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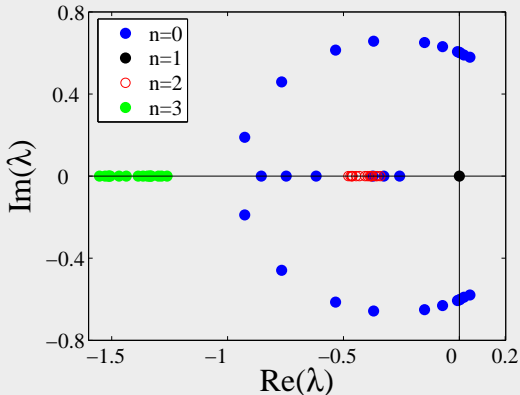
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- $\lambda = 0 \Rightarrow \mu_{1,2} = \left\{0, \frac{\kappa_3 \tau - 1}{\tau}\right\} \Rightarrow f_{v1,2} = f_u$ .
- Propagator mode: Generalized eigenfunction

$$\mathcal{L}'(\mathbf{u}_s) \mathcal{L}'(\mathbf{u}_s) \mathcal{P}_r = 0 \Rightarrow \mathcal{L}'(\mathbf{u}_s) \mathcal{P}_r = \mathcal{G}_r$$

# Breathing DSs

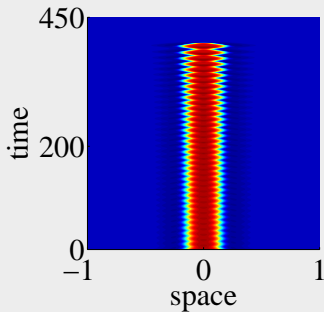
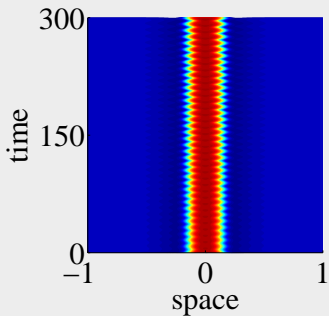
- Destabilization via the mode  $n = 0$ :







## Breathing DSs



## Amplitude equation

The idea:

- Two-scale expansion in the vicinity of bifurcation point,

$$\theta = \theta_c: \tilde{\mathbf{u}} = Ae^{i\omega t}\mathcal{F}_c + c.c. + r$$

$$\theta = \theta_c + \varepsilon: \tilde{\mathbf{u}} = A(t)e^{i\omega t}(\mathcal{F}_c + \varepsilon\mathcal{F}_\varepsilon) + c.c. + r;$$

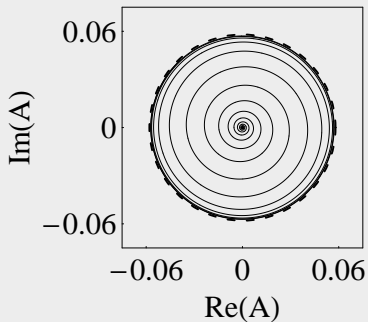
- Amplitude equation is a normal form of a Hopf bifurcation;
- Complex coefficients can be immediately evaluated if the solitary stationary solution is known;

$$\partial_t A = \varepsilon a_1 A + a_2 A |A|^2,$$

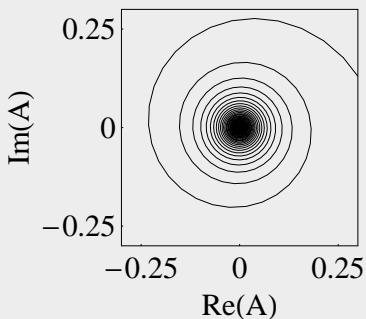
$$a_1 = \frac{\langle \mathcal{L}'_\varepsilon(\mathbf{u}_s)\mathcal{F}_c | \mathcal{F}_c^* \rangle}{\langle \mathcal{F}_c | \mathcal{F}_c^* \rangle}, \quad a_2 = \frac{\langle \mathcal{L}'''_c(\mathbf{u}_s)\mathcal{F}_c\mathcal{F}_c\overline{\mathcal{F}_c} | \mathcal{F}_c^* \rangle}{2\langle \mathcal{F}_c | \mathcal{F}_c^* \rangle}.$$

## Amplitude equation

$$\operatorname{Re}(a_1) < 0, \operatorname{Re}(a_2) > 0$$

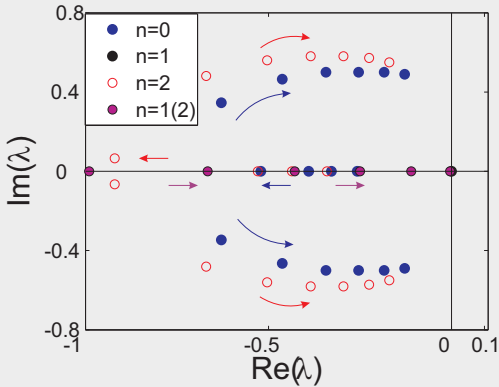


$$\operatorname{Re}(a_1) < 0, \operatorname{Re}(a_2) < 0$$



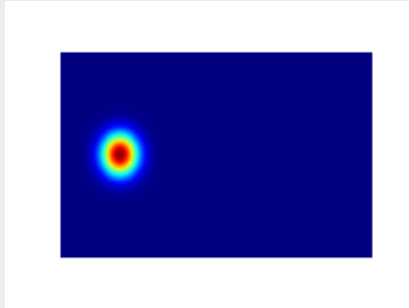
## Moving DSs

- Destabilization via the mode  $n = 1$ :



# Moving DSs

- Destabilization via the mode  $n = 1$ :



## Moving DSs: Drift-Bifurcation

- Fredholm alternative:

$$\mathcal{L}'(\mathbf{u}_s)\mathcal{P}_r = \mathcal{G}_r \Leftrightarrow \langle \mathcal{G}_r^* | \mathcal{G}_r \rangle = 0$$

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$$\tau_{c,x} = \frac{1}{\kappa_3} - \theta \frac{\kappa_4 \langle w_{s,x}^2 \rangle}{\kappa_3 \langle u_{s,x}^2 \rangle}$$

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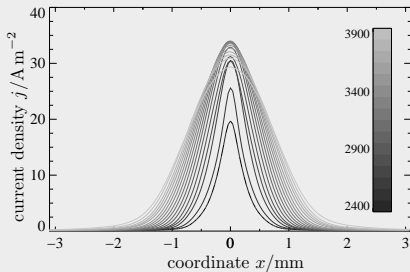
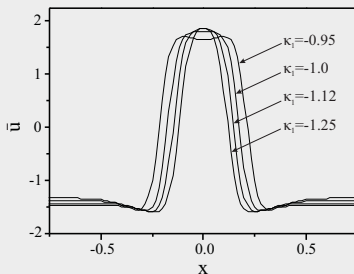
- Propagation velocity:

$$c^2 = \frac{\kappa_3}{\tau_{c,x}^2} \frac{\langle u_{s,x}^2 \rangle}{\langle u_{s,xx}^2 \rangle} \left( \tau - \tau_{c,x} \right)$$

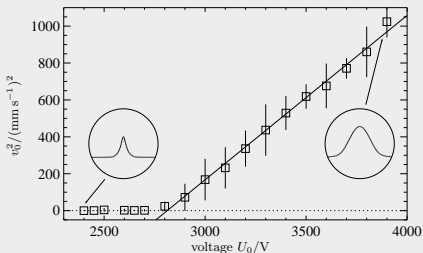
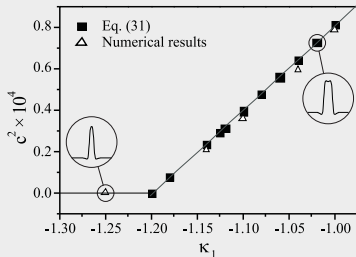




# Drift-Bifurcation due to a change of shape

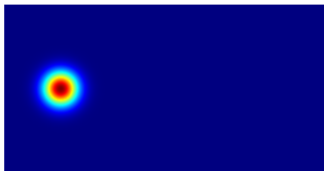
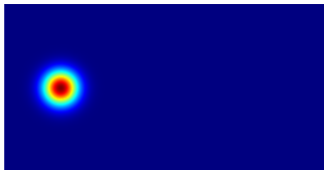


# Drift-Bifurcation due to a change of shape





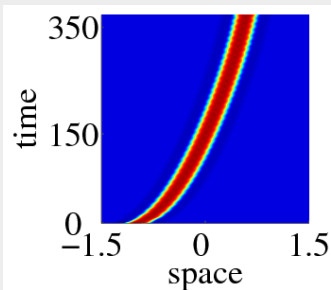
# Breathing and moving DSs



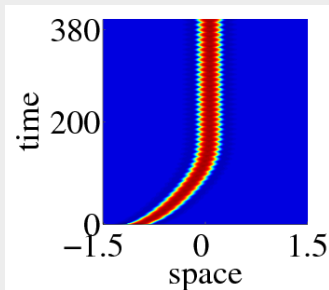


## Breathing and moving DSs

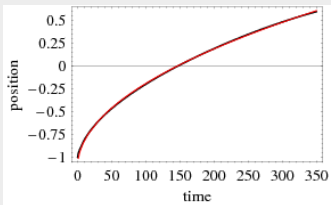
(a)



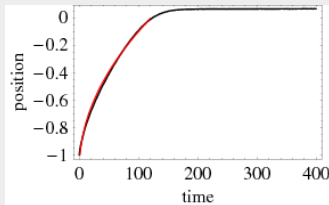
(b)

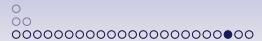


(c)

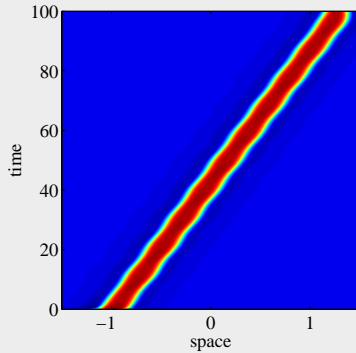


(d)



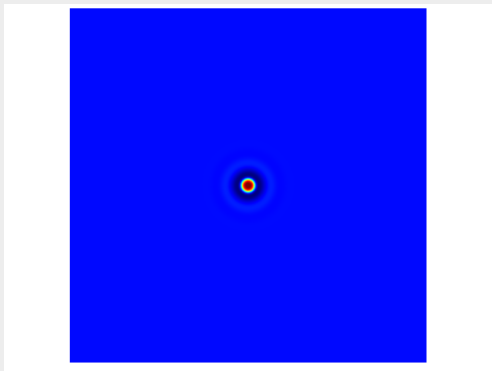


# Breathing and moving DSs





# Breathing DSs with oscillatory tails





## Breathing DSs with oscillatory tails

