

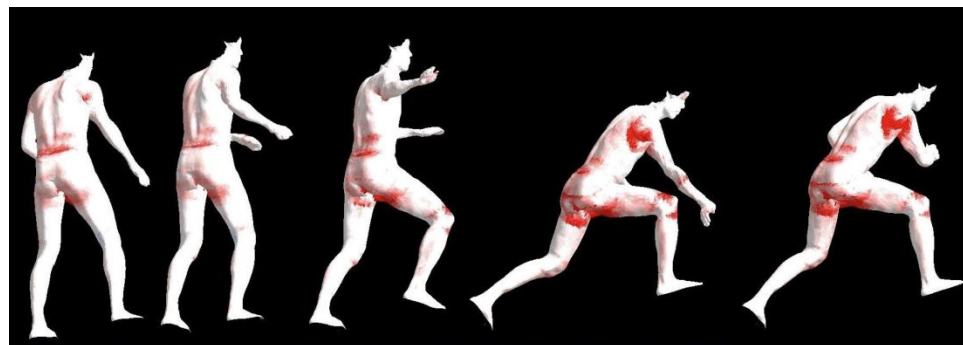
Optimal Decoding of Stripe Patterns with Window Uniqueness Constraint

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One-shot depth acquisition

❑ Structured Light for Moving Objects



Spatially-Coded Illumination

1D Discrete

- De Bruijn sequence

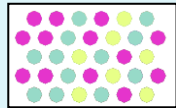


[Hugli 1989] [Zhang 2002]
[Lim 2009] [Yamazaki 2011]

 Dense & Robust

2D Discrete

- M-array



[Griffin 1992] [Morano 1998]
[Pages 2006] [Kinect]

- Non-formal



[Maruyama 1995]
[Forster 2007] [Sagawa 2012]
[Kawasaki 2008]

 Very Robust
 Sparse

Continuous

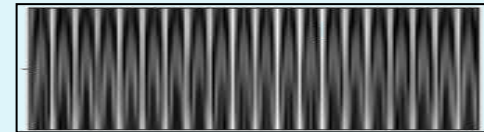
- Phase-shifting

[Wust 1991]
[Guan 2004]



- Frequency-multiplexing



[Takeda 1983] [Gdeisat 2006]
[Berryman 2008] [Zhang 2008]
[Wu 2006] [Cobelli 2009]



- Spatial multiplexing

[Carrihill 1985] [Tajima 1990]



 Subpixel
 Sensitive

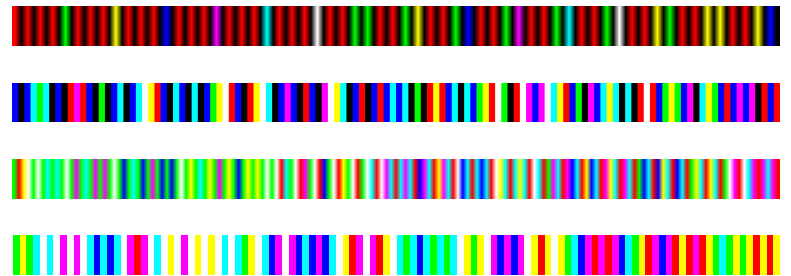
De Bruijn Color Code

- De Bruijn sequence $B(k, n)$
 - Cyclic sequence
 - Composed of symbols with size k
 - Unique subsequence of length n

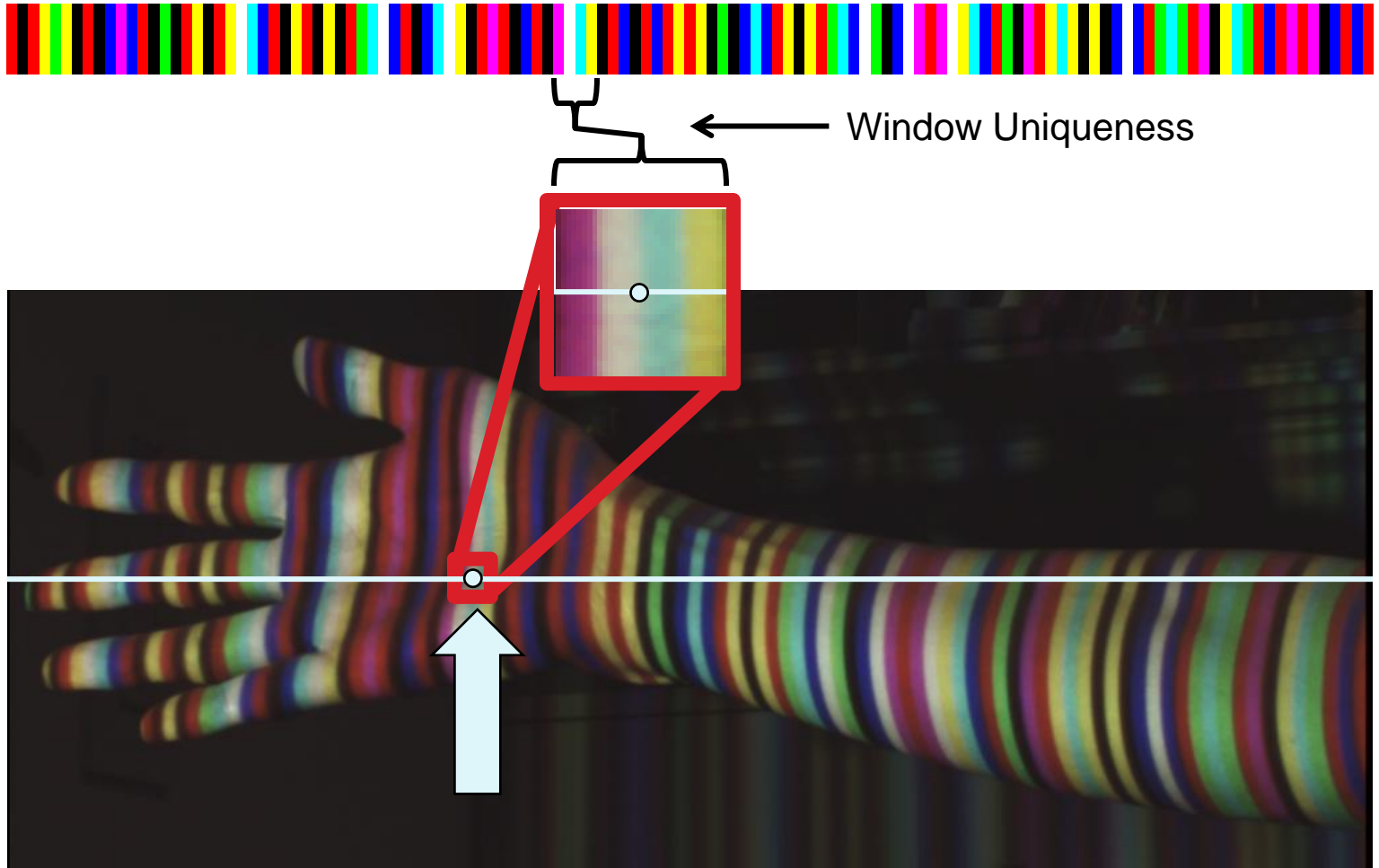
$$B(5,3) = \{ \dots, 2, 0, 0, 3, 0, 0, 4, 0, 1, 1, 0, 1, 2, 0, 1, 3, 0, 1, 4, 0, 2, \dots \}$$

Window Uniqueness Property

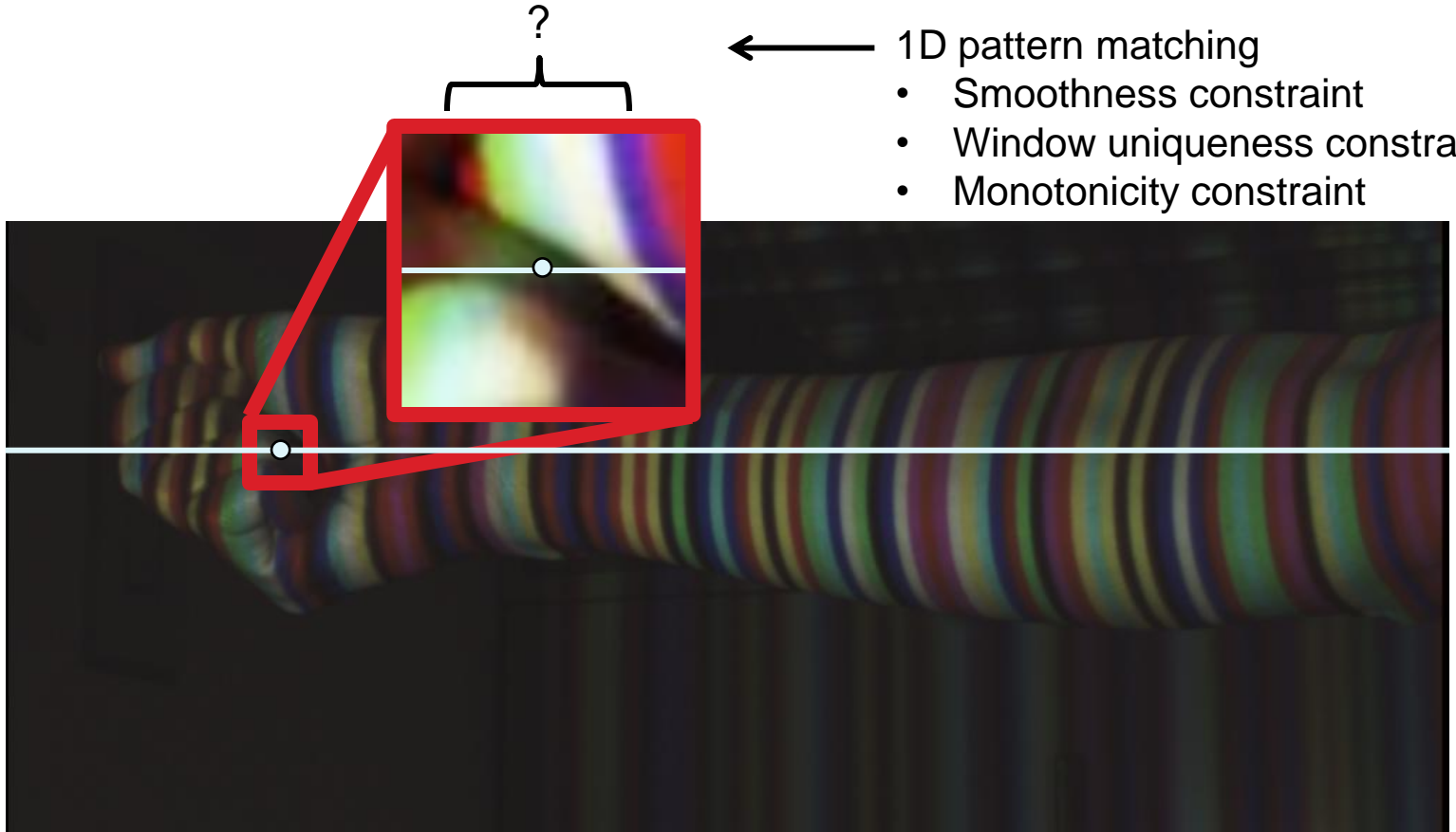
- Color Stripes
 - Direct [Hugli 1989]
 - XOR [Zhang 2002]
 - Non-recurring [Lim 2009]
 - Hamming [Yamazaki 2011]



Decoding Structured Light



Decoding Structured Light



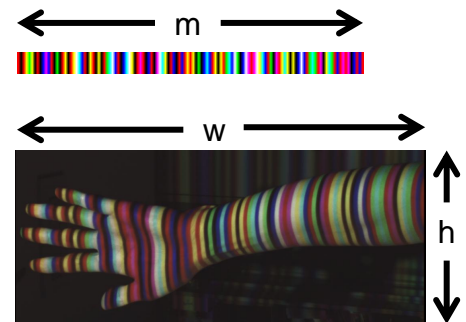
- ← 1D pattern matching
- Smoothness constraint
 - Window uniqueness constraint
 - Monotonicity constraint

Decoding Structured Light

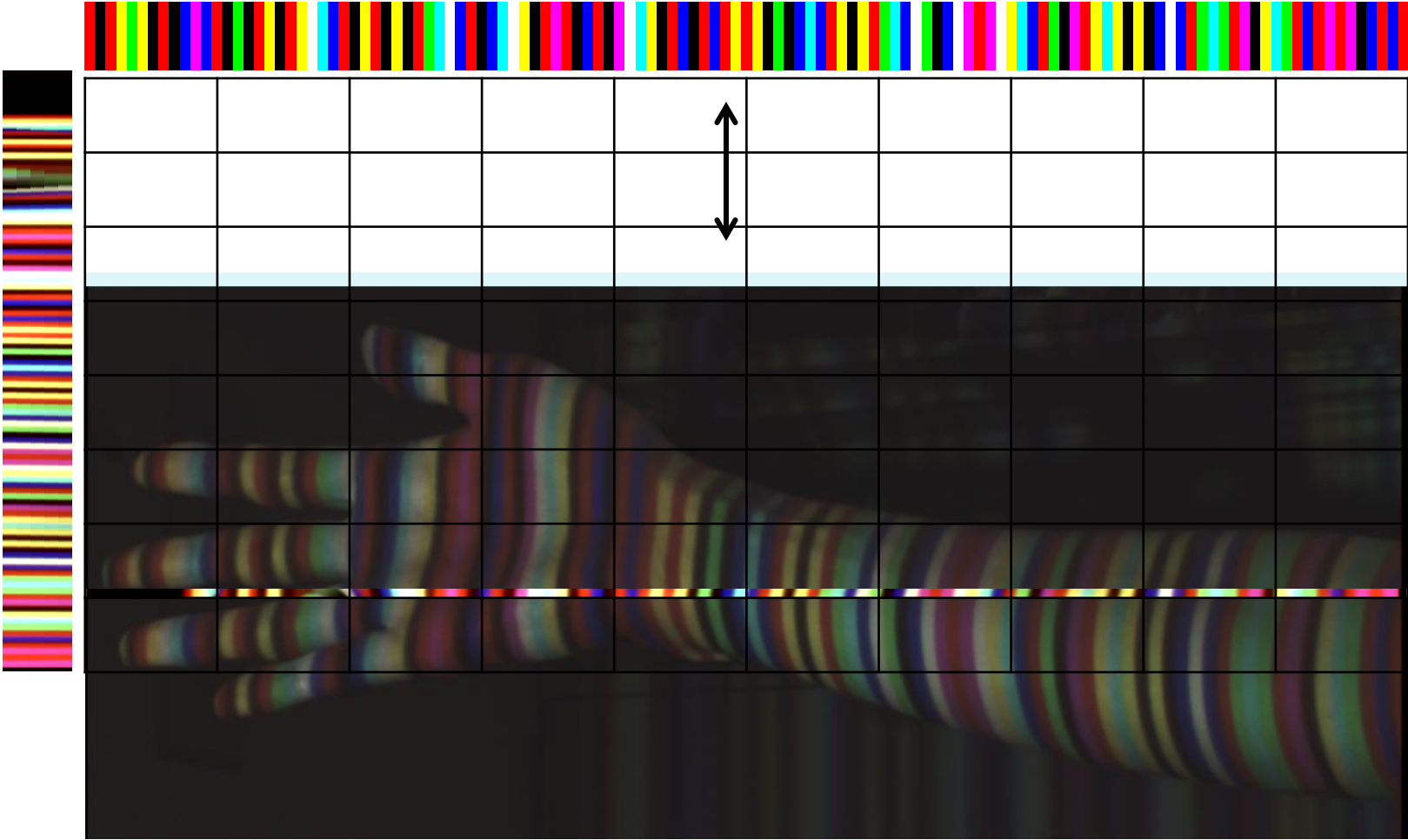
- ❑ Global optimization
 - Annealing, Graph-cut, Belief propagation, etc.
 - High computational cost
 - Convergence not guaranteed

- ❑ Greedy search
 - propagates local reconstruction [Forster 2006]
 - sometimes yields better results than the global methods [Schmalz 2010]
 - 10+ FPS by CPU implementation

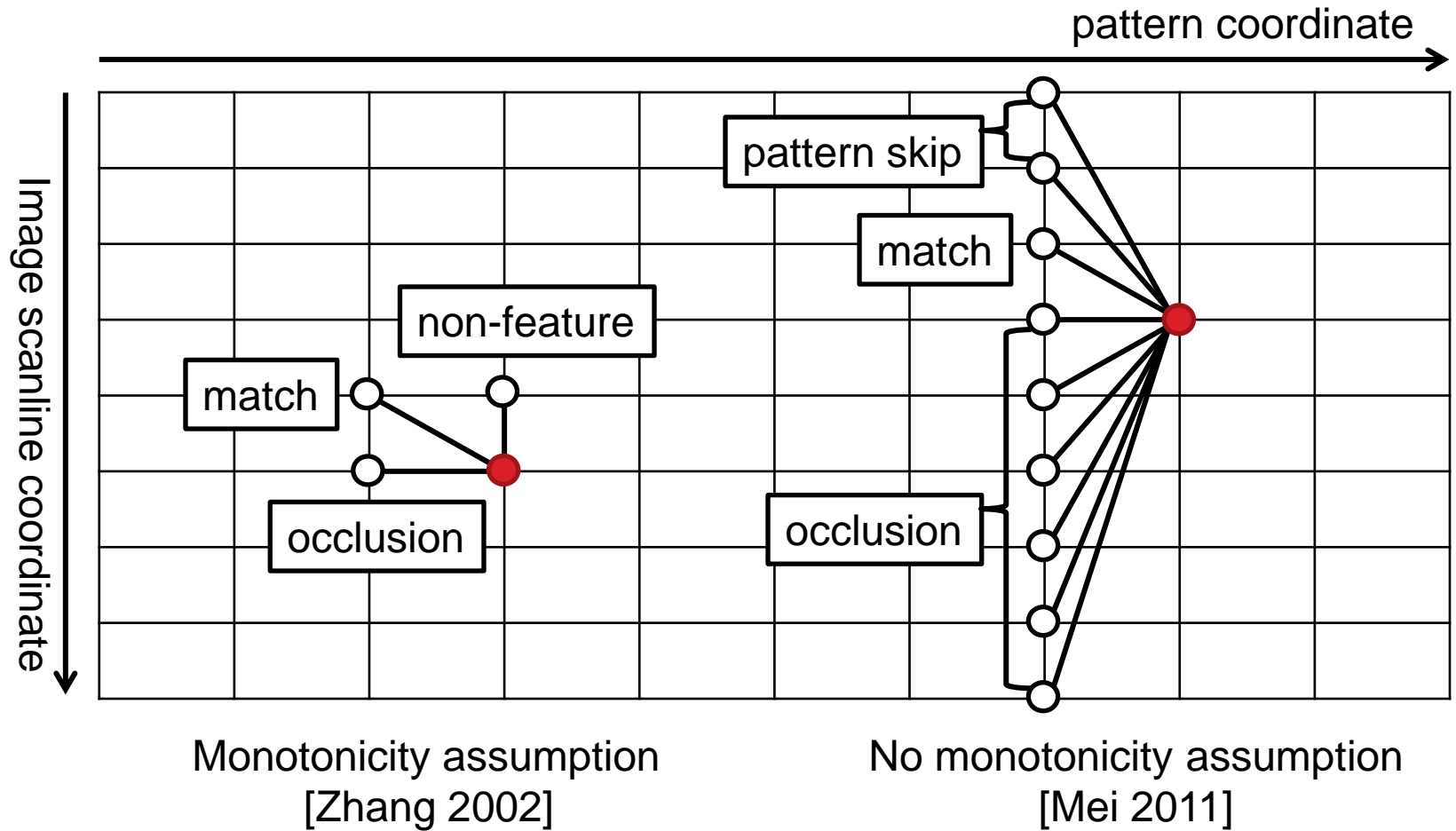
- ❑ Dynamic Programming Matching (DPM)
 - Optimal, pseudo linear algorithm : $O(whm)$
 - Monotonicity assumption
 - Multipass DP [Zhang 2002] : $O(whm)$
 - Non-monotonic DP [Mei 2011] : $O(w^2hm)$
 - 60+ FPS by GPU implementation [Yamazaki 2011]



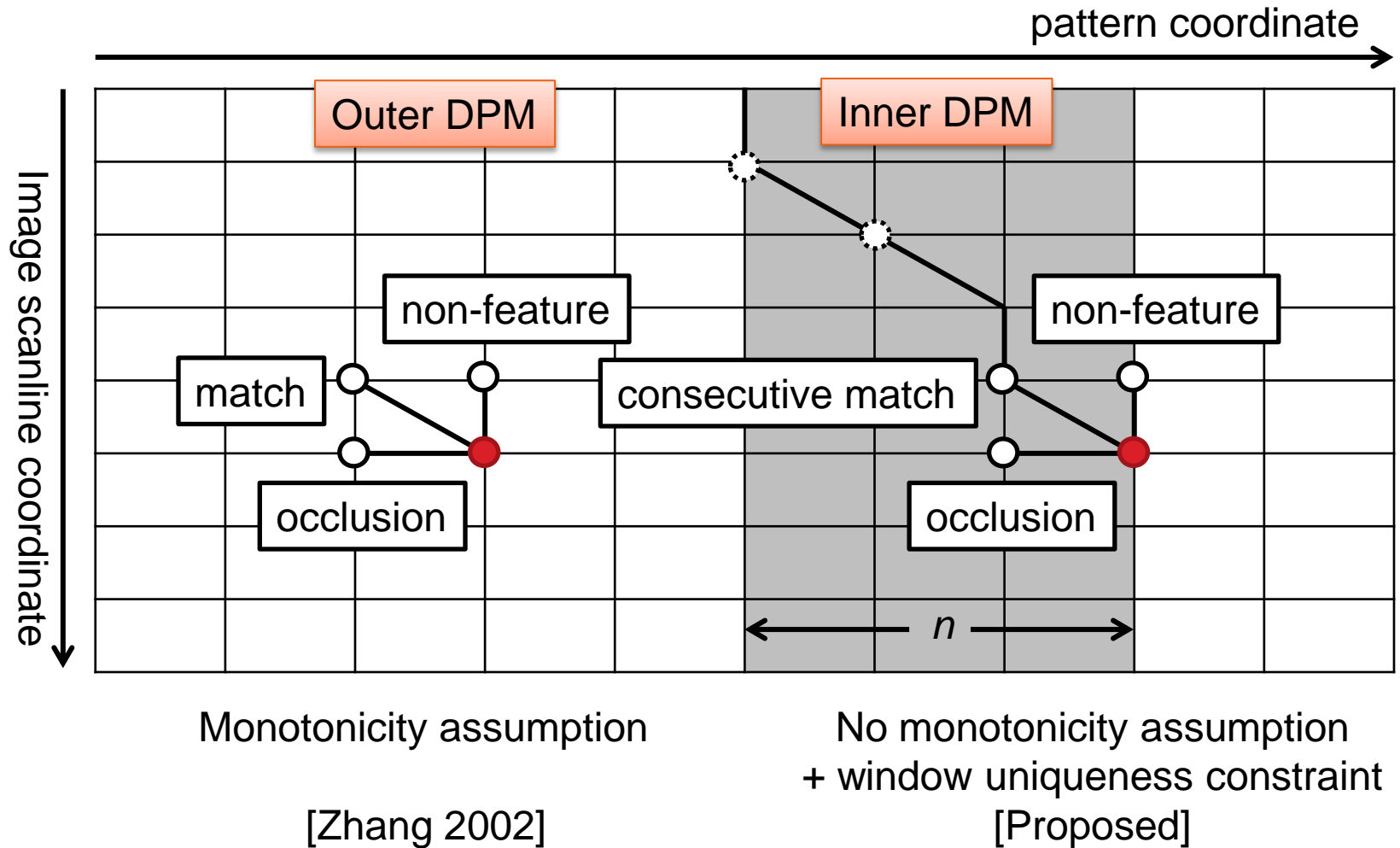
Dynamic Programming



Dynamic Programming

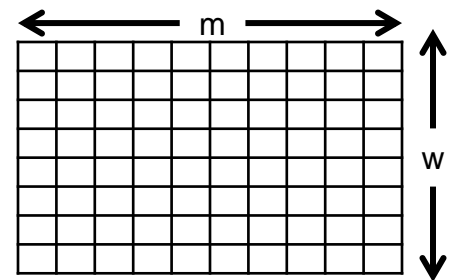
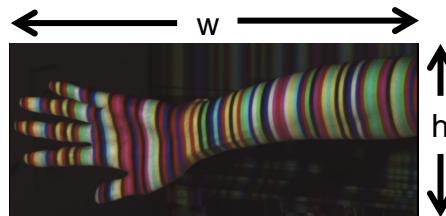


Proposed DPM



Computational Complexity

- For each scanline
 - Generate DPM table T : h
 - For each column r in T : $O(wm)$
 - Solve Inner DPM : m
 - For each row r in c : $O(w)$
 - Find the optimal solution : w
 - Backtrack : $O(1)$
 - Backtrack : $O(w)$
- } $O(whm)$

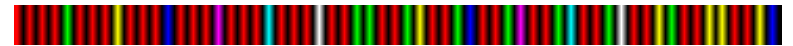


Same complexity as conventional DPM

Experiments

□ Color Stripes based on De Bruijn sequences (n=4)

– Direct [Hugli 1989]



- $\{1, \dots, 7\} = \{001, \dots, 111\} = \{\text{red}, \dots, \text{white}\}$
- Black separators inserted

– XOR [Zhang 2002]



- $\{1, \dots, 7\} = \{\oplus 001, \dots, \oplus 111\}$
- Encoded into stripe borders

– Non-recurring [Lim 2009]



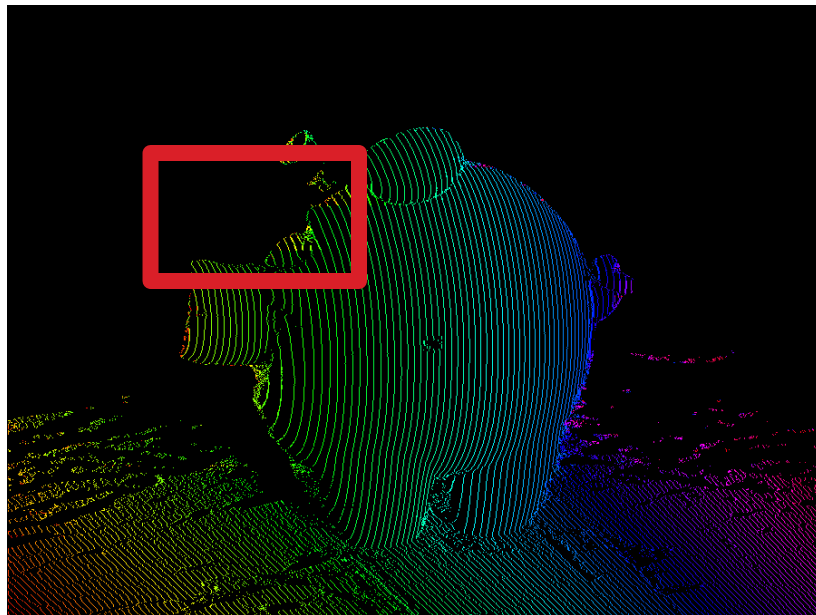
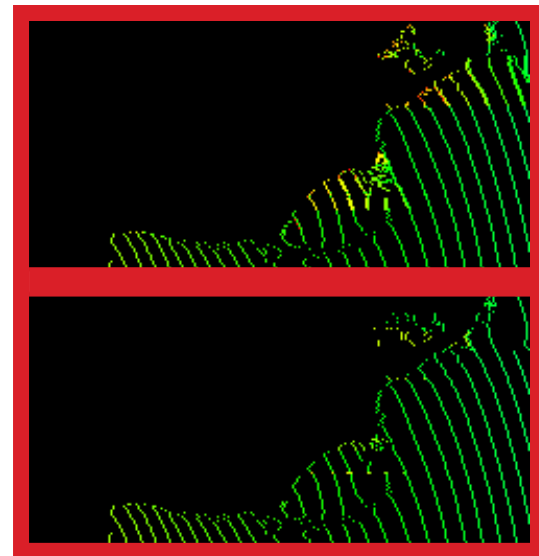
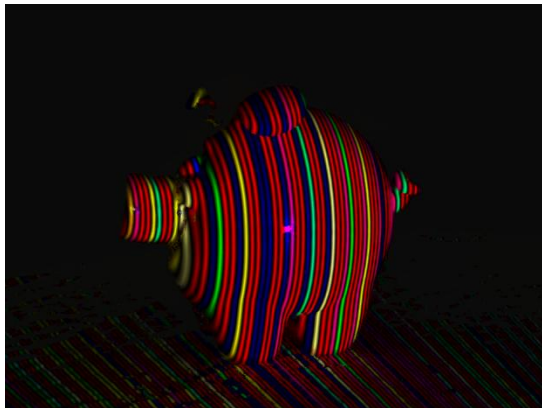
- Eliminated consecutive symbols from a De Bruijn sequence

– Hamming [Yamazaki 2011]

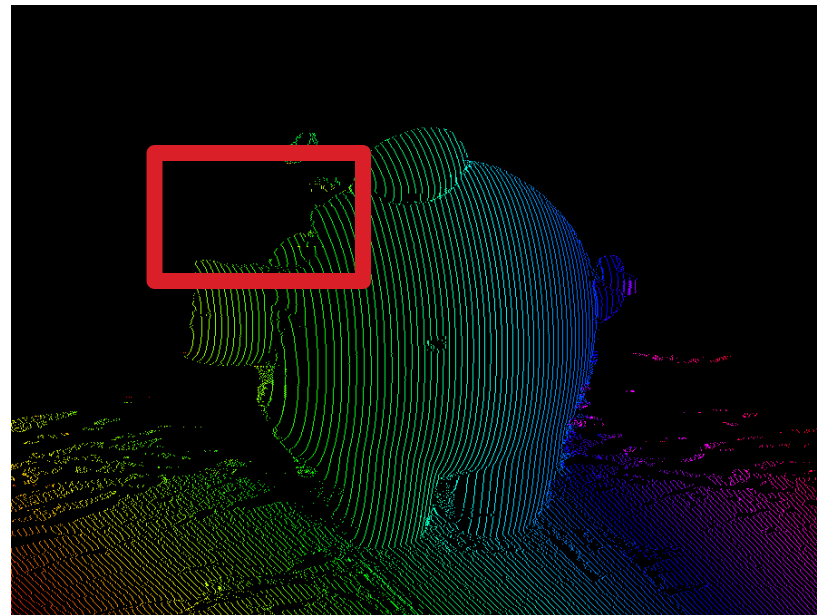


- Eliminated simultaneous bit flips from a De Bruijn sequence

Result - Direct

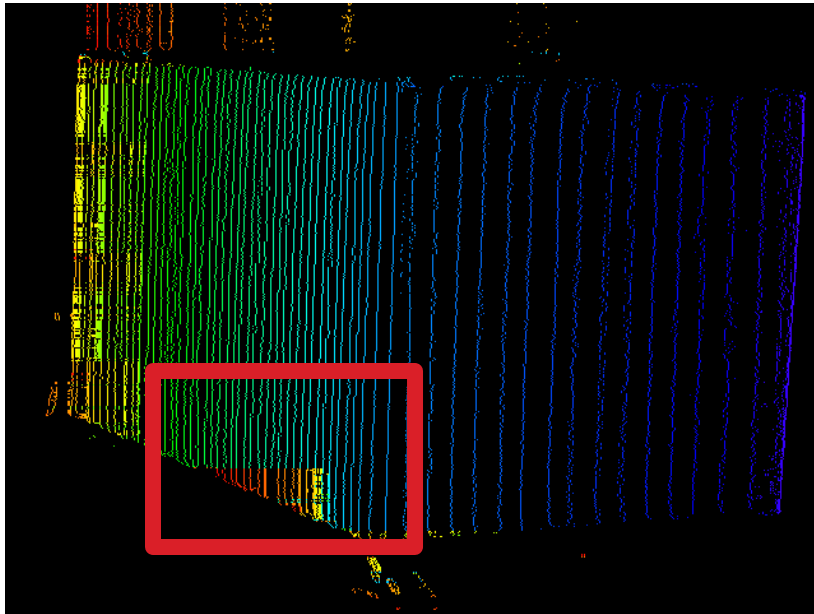
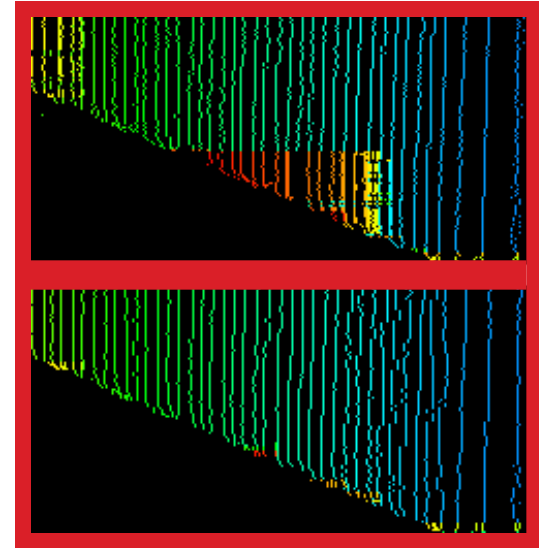


Conventional DPM

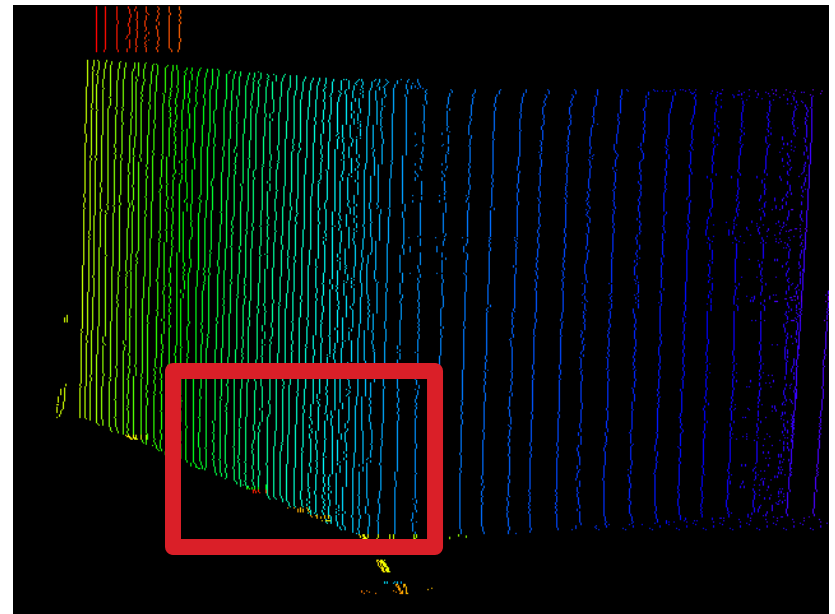


Proposed

Result - XOR

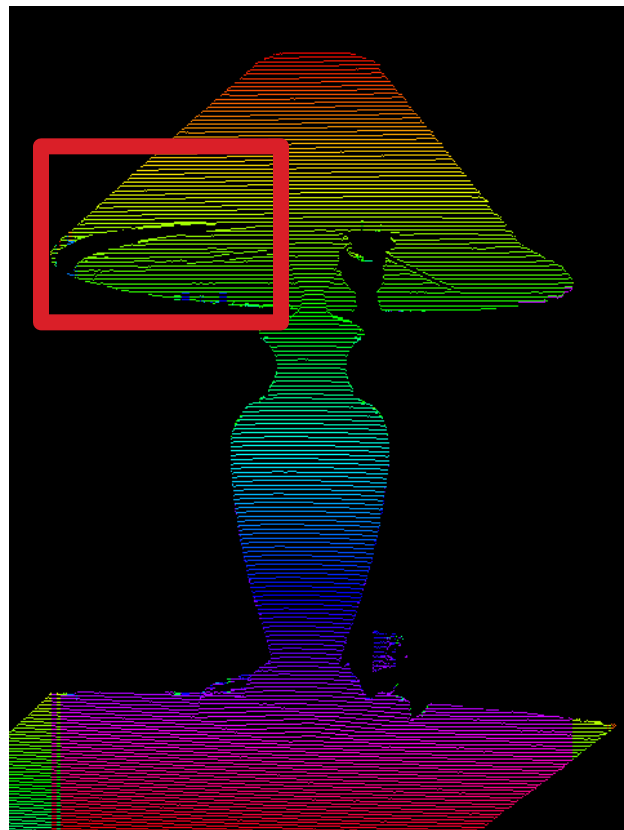
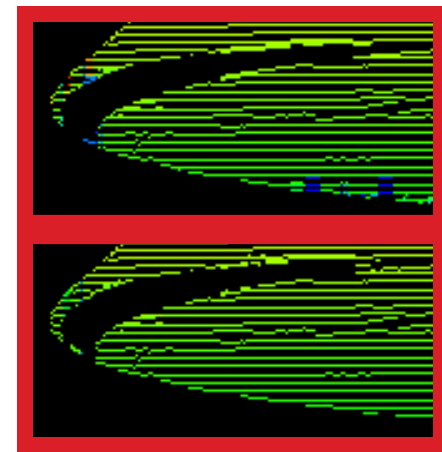


Conventional DPM

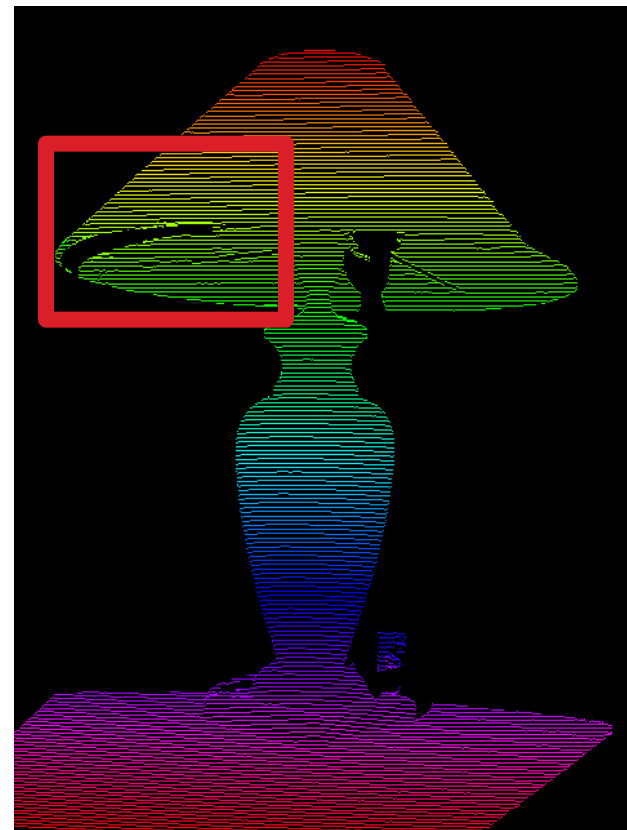


Proposed

Result – Non-recurring

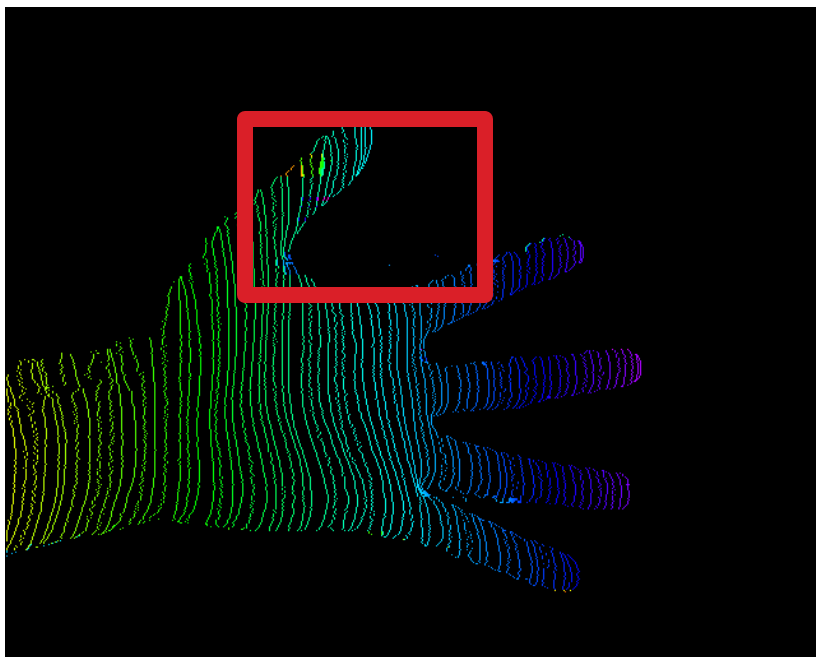
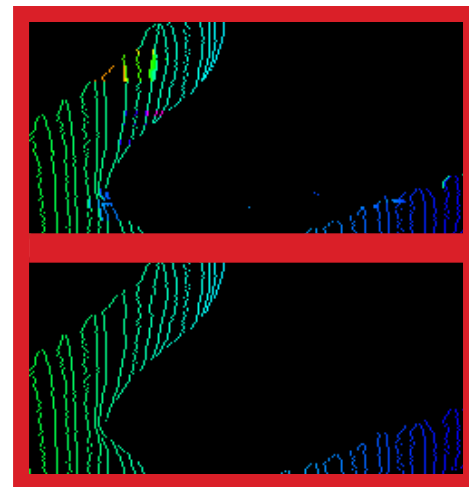
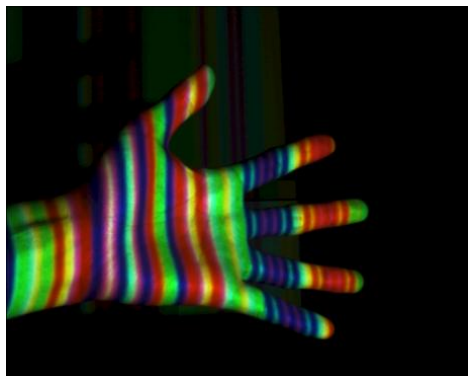


Conventional DPM

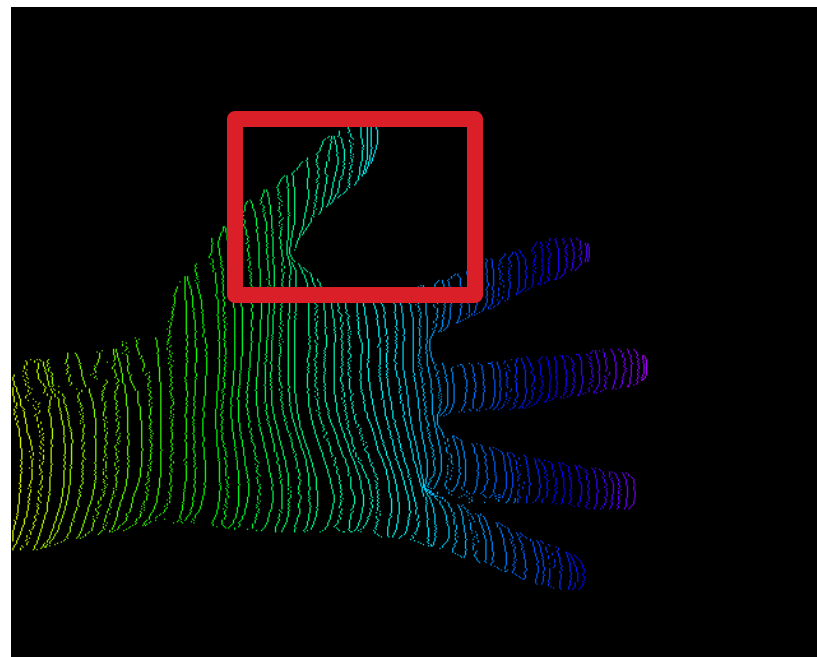


Proposed

Result – Hamming



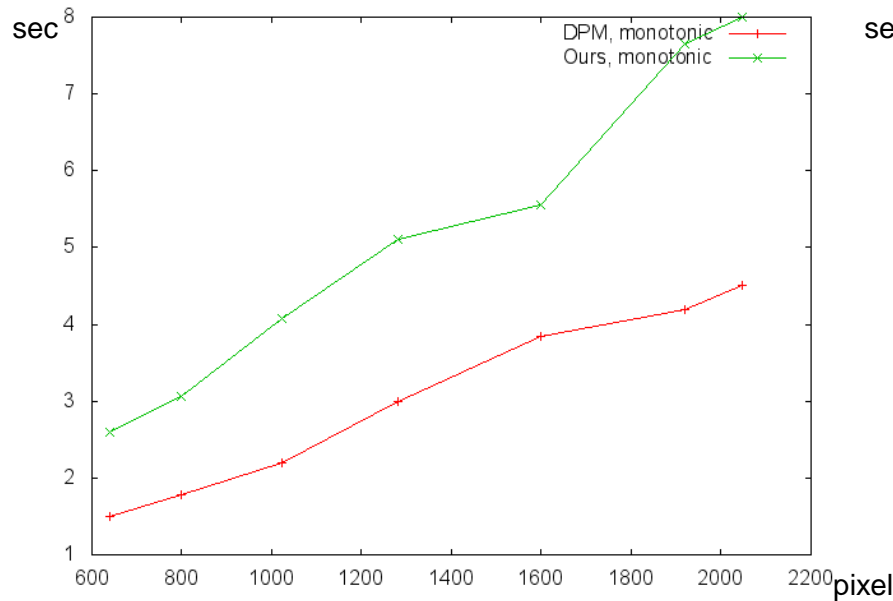
Conventional DPM



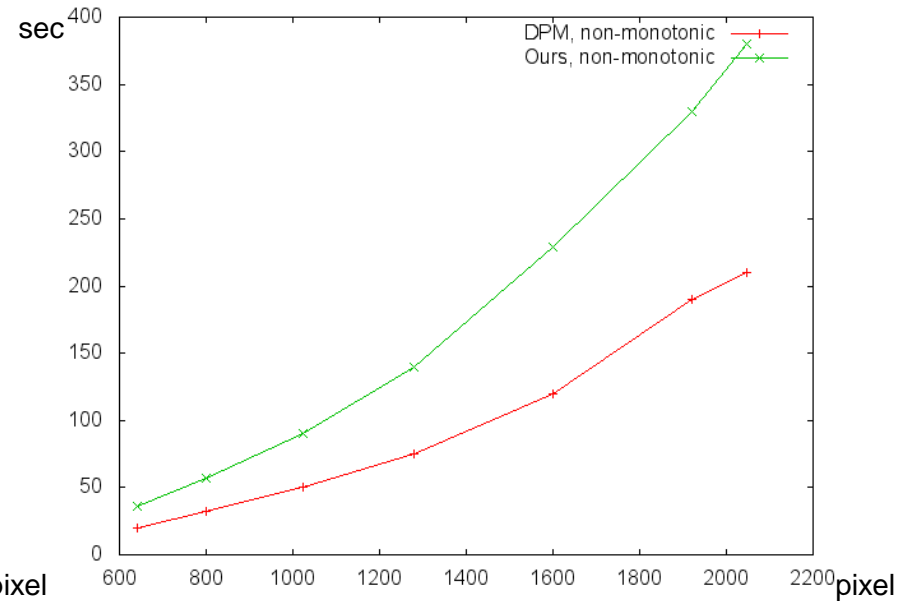
Proposed

Timing

- CPU: Intel Core i7 X940 2.13GHz
- Input:
 - Image width : $w = 640 \sim 2048$
 - Image height : $h = 480$
 - Code length : $m = 110$
 - Window uniqueness : $n = 4$



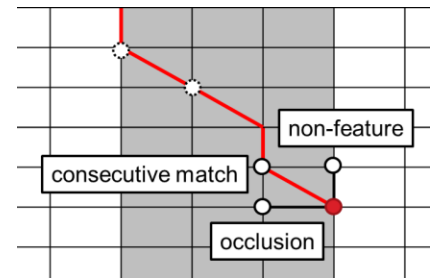
Monotonicity assumption : $O(w hm)$



No monotonicity assumption : $O(w^2 hm)$

Discussion

- ❑ Significant improvement on depth boundaries.
 - ❑ The boundaries are **always** unreliable in the conventional DPM.
- ❑ 2 ~ 3 time longer computation time
 - ❑ Additional data structure is required for the path of consecutive matches.
 - ❑ GPU-implementation for real-time reconstruction
- ❑ Subtle improvement ?
 - ❑ Conventional DPM is tuned for fair comparison.
 - ❑ Penalty for pattern break
 - ❑ Range of stripe interval
- ❑ Streaking artifacts
 - ❑ Fundamental limitation of scanline-based algorithm
 - ❑ Considering inter-scanline consistency
- ❑ Quantitative comparison missing



Conclusion

- ❑ Two-level Dynamic Programming Matching
 - Optimal decoding of color stripes
 - Window uniqueness constraint
 - Same complexity as conventional methods : $O(whm)$

- ❑ Applicable to several systems
 - Independent of color stripes
 - Demonstration using 4 different patterns
 - Achieved better results with little additional cost

- ❑ Optimal v.s. Sub-optimal
 - Combination with sub-optimal algorithms for inter-scanline consistency

- ❑ Practical issues
 - Constant factors matter
 - Efficient implementation required