On Higher-Order Probabilistic Computation: Relational Reasoning, Termination, and Bayesian Programming

Ugo Dal Lago

(Based on joint work with Michele Alberti, Raphaëlle Crubillé, Charles Grellois, Davide Sangiorgi,...)



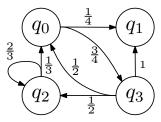
IFIP WG 2.2 Annual Meeting, Brno, September 17th

► The **environment** is supposed not to behave *deterministically*, but *probabilistically*.

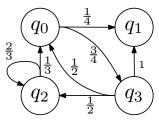
- ► The **environment** is supposed not to behave *deterministically*, but *probabilistically*.
- Crucial when modeling **uncertainty**.

- ► The **environment** is supposed not to behave *deterministically*, but *probabilistically*.
- Crucial when modeling **uncertainty**.
- Useful to handle **complex** domains.

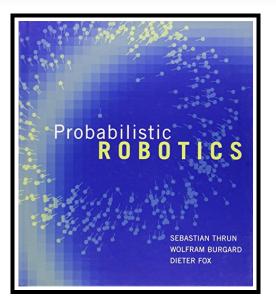
- ► The **environment** is supposed not to behave *deterministically*, but *probabilistically*.
- Crucial when modeling **uncertainty**.
- ▶ Useful to handle **complex** domains.
- Example:



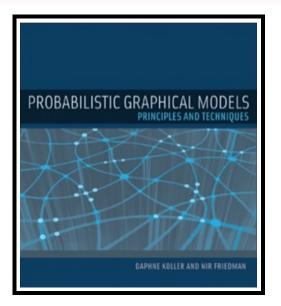
- ► The **environment** is supposed not to behave *deterministically*, but *probabilistically*.
- Crucial when modeling **uncertainty**.
- ▶ Useful to handle **complex** domains.
- Example:



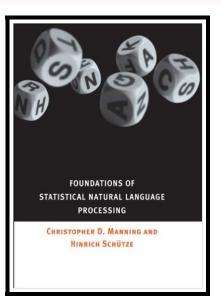
- Abstractions:
 - ▶ (Labelled) Markov Chains.



ROBOTICS



ARTIFICIAL INTELLIGENCE



LANGUAGE ΓT NATU PROC

▶ Algorithms and automata are assumed to have the ability to **sample** from a distribution [dLMSS1956,R1963].

- ▶ Algorithms and automata are assumed to have the ability to **sample** from a distribution [dLMSS1956,R1963].
- ► This is a **powerful tool** when solving computational problems.

- ▶ Algorithms and automata are assumed to have the ability to **sample** from a distribution [dLMSS1956,R1963].
- ► This is a **powerful tool** when solving computational problems.
- Example:

```
Input: n > 3, an odd integer to be tested for primality;

Input: n > 3, an arameter that determines the accuracy of the test

Output: composite if n is composite, otherwise probably prime

write n - 1 as 2^{n-4} with d odd by factoring powers of 2 from n - 1

WitnessLoop: repeat k times:

pick a random integer a in the range [2, n - 2]

x - a^{d} \mod n

if x = 1 or x = n - 1 then do next WitnessLoop

repeat s - 1 times:

x - x^{2} \mod n

if x = 1 then return composite

if x = n - 1 then do next WitnessLoop

return composite

return composite
```

- ▶ Algorithms and automata are assumed to have the ability to **sample** from a distribution [dLMSS1956,R1963].
- ► This is a **powerful tool** when solving computational problems.
- Example:

```
Imput: n > 3, an odd integer to be tested for primality;

Imput: n > 3, parameter that determines the accuracy of the test

Output: composite if n is composite, otherwise probably prime

write n - 1 as 2*-4 with d odd by factoring powers of 2 from n - 1

witnessLoop: repeat X times:

Pick a random integer a in the range [2, n - 2]

a x - a^{2} \mod n

if x = 1 or x = n - 1 then do next WitnessLoop

repeat s - 1 times:

x - x^{2} \mod n

if x = 1 then return composite

if x = n - 1 then do next WitnessLoop

return probably prime
```

- ▶ Algorithms and automata are assumed to have the ability to **sample** from a distribution [dLMSS1956,R1963].
- ► This is a **powerful tool** when solving computational problems.
- Example:

```
Imput: n > 3, an odd integer to be tested for primality;

Imput: n > 3, parameter that determines the accuracy of the test

Output: composite if n is composite, otherwise probably prime

write n - 1 as 2*-4 with d odd by factoring powers of 2 from n - 1

WitnessLoop: repeat k times:

Pick a random integer a in the range [2, n - 2]

if x = 1 or x = n - 1 then do next WitnessLoop

repeat s - 1 times:

x - a^{2} \mod n

if x = 1 then return composite

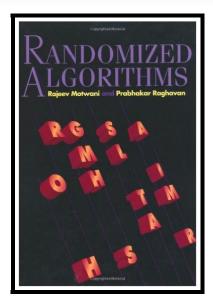
if x = 1 then return composite

if x = n - 1 then do next WitnessLoop

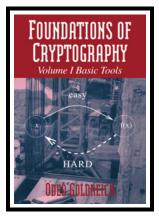
return probably prime
```

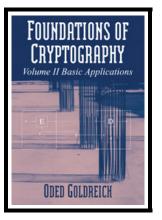
Abstractions:

- Randomized algorithms;
- Probabilistic Turing machines.
- Labelled Markov chains.

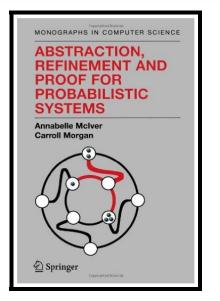


ALGORITHMICS





CRYPTOGRAPHY



PROGRAM VERIFICATION

• Mainly useful in **programming**.

- Mainly useful in **programming**.
- ► Functions are **first-class citizens**:
 - ▶ They can be passed as *arguments*;
 - ▶ They can be obtained as *results*.

- Mainly useful in **programming**.
- ► Functions are **first-class citizens**:
 - ▶ They can be passed as *arguments*;
 - They can be obtained as *results*.

Motivations:

- ► Modularity;
- ► Code reuse;
- ► Conciseness.

- Mainly useful in **programming**.
- ▶ Functions are **first-class citizens**:
 - ▶ They can be passed as *arguments*;
 - They can be obtained as *results*.

Motivations:

- Modularity;
- ► Code reuse;
- ► Conciseness.

• Example:

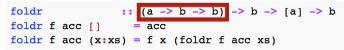
foldr :: (a -> b -> b) -> b -> [a] -> b
foldr f acc [] = acc
foldr f acc (x:xs) = f x (foldr f acc xs)

- Mainly useful in **programming**.
- ▶ Functions are **first-class citizens**:
 - ▶ They can be passed as *arguments*;
 - ▶ They can be obtained as *results*.

Motivations:

- ► Modularity;
- ► Code reuse;
- ► Conciseness.

• Example:

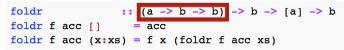


- Mainly useful in **programming**.
- ► Functions are **first-class citizens**:
 - ▶ They can be passed as *arguments*;
 - ▶ They can be obtained as *results*.

Motivations:

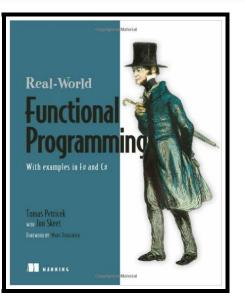
- ► Modularity;
- ► Code reuse;
- ► Conciseness.

• Example:

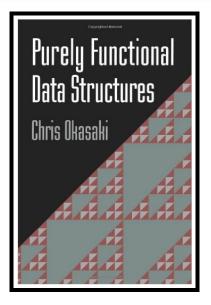


Models:

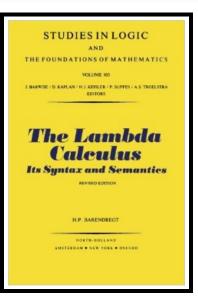
• λ -calculus



FUNCTIONAL PROGRAMMING



URES



A-CALCULUS

Higher-Order Probabilistic Computation

Does it Make Sense?

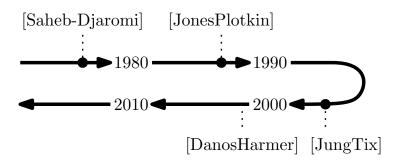
Higher-Order Probabilistic Computation

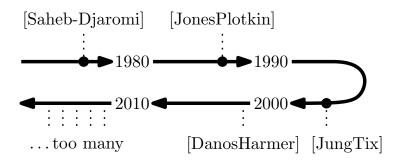
Does it Make Sense? What Kind of Metatheory Does it Have?

Higher-Order Probabilistic Computation

Does it Make Sense? What Kind of Metatheory Does it Have?

Applications?





Part I Relational Reasoning

Part II Bayesian Functional Programming

Part III Termination

Part I

Relational Reasoning

Syntax and Operational Semantics of Λ_\oplus

► Terms:
$$M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$$

Syntax and Operational Semantics of Λ_{\oplus}

- ► Terms: $M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$
- Values: $V ::= \lambda x.M;$

Syntax and Operational Semantics of Λ_{\oplus}

- ► Terms: $M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$
- Values: $V ::= \lambda x.M;$
- ► Value Distributions:

$$V \xrightarrow{\mathcal{D}} \mathcal{D}(V) \in \mathbb{R}_{[0,1]}$$

$$\sum \mathcal{D} = \sum_{V} \mathcal{D}(V) \le 1.$$

- ► Terms: $M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$
- Values: $V ::= \lambda x.M;$
- ▶ Value Distributions:

$$V \stackrel{\mathcal{D}}{\longrightarrow} \mathcal{D}(V) \in \mathbb{R}_{[0,1]}$$

$$\sum \mathcal{D} = \sum_{V} \mathcal{D}(V) \le 1.$$

• Semantics: $\llbracket M \rrbracket = \sup_{M \Downarrow \mathcal{D}} \mathcal{D};$

$$\frac{\overline{M \Downarrow \emptyset}}{\overline{W \Downarrow \emptyset}} \frac{\overline{W \Downarrow \{V^1\}}}{\overline{W \Downarrow \{V^1\}}} \frac{\overline{M \Downarrow \mathfrak{D}} N \Downarrow \mathfrak{E}}{\overline{M \oplus N \Downarrow \frac{1}{2} \mathfrak{D} + \frac{1}{2} \mathfrak{E}}} \\
\frac{\overline{M \Downarrow \mathscr{K}}}{\overline{MN \Downarrow \sum_{\lambda x. P \in \mathbf{S} \mathscr{K}}} \mathscr{K}(\lambda x. P) \cdot \mathscr{E}_P} \\
\frac{\overline{M \lor \mathscr{K}}}{\overline{V \lor (V \lor \mathbb{IN}[0,1]}} \frac{\overline{\mathcal{L}}}{\overline{V} \lor \mathbb{IN}[0,1]} (V) \leq 1.$$

• Semantics: $\llbracket M \rrbracket = \sup_{M \Downarrow \mathcal{D}} \mathcal{D};$

- ► Terms: $M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$
- Values: $V ::= \lambda x.M;$
- ► Value Distributions:

$$V \xrightarrow{\mathcal{D}} \mathcal{D}(V) \in \mathbb{R}_{[0,1]} \qquad \qquad \sum \mathcal{D} = \sum_{V} \mathcal{D}(V) \le 1.$$

- Semantics: $\llbracket M \rrbracket = \sup_{M \Downarrow \mathcal{D}} \mathcal{D};$
- Context Equivalence: $M \equiv N$ iff for every context C it holds that $\sum [\![C[M]]\!] = \sum [\![C[N]]\!]$.

- Terms: $M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$
- Values: $V ::= \lambda x.M$;
- Value Distributions:

$$C ::= [\cdot] \mid \lambda x.C \mid CM \mid MC \mid C \oplus M \mid M \oplus C \bigvee^{V} \leq 1$$

- Semantics: [[M]] = sup_{NUD} D;
 Context Equivalence: M ≡ N iff for every context C it holds that ∑[[C[M]]] = ∑[[C[N]]].

- ► Terms: $M ::= x \mid \lambda x.M \mid MM \mid M \oplus M;$
- Values: $V ::= \lambda x.M;$
- ▶ Value Distributions:

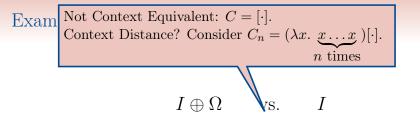
$$V \xrightarrow{\mathcal{D}} \mathcal{D}(V) \in \mathbb{R}_{[0,1]} \qquad \qquad \sum \mathcal{D} = \sum_{V} \mathcal{D}(V) \le 1.$$

- Semantics: $\llbracket M \rrbracket = \sup_{M \Downarrow \mathcal{D}} \mathcal{D};$
- Context Equivalence: $M \equiv N$ iff for every context C it holds that $\sum [\![C[M]]\!] = \sum [\![C[N]]\!]$.
- Context Distance: $\delta^C(M, N) = \sup_C |\sum \llbracket C[M] \rrbracket - \sum \llbracket C[N] \rrbracket|.$

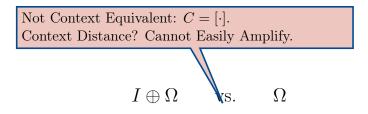
$I \oplus \Omega$ vs. I



$$\Delta \Delta = (\lambda x.xx)(\lambda x.xx)$$
$$I \oplus \Omega \quad \text{vs.} \quad I$$



$I \oplus \Omega$ vs. I $I \oplus \Omega$ vs. Ω



$I \oplus \Omega$ vs. I

$I \oplus \Omega$ vs. Ω

 $(\lambda x.I) \oplus (\lambda x.\Omega)$ vs. $\lambda x.I \oplus \Omega$

$I \oplus \Omega$ vs. I

Not Context Equivalent in CBV: $C = (\lambda x.x(xI))[\cdot]$ Apparently Context Equivalent in CBN.

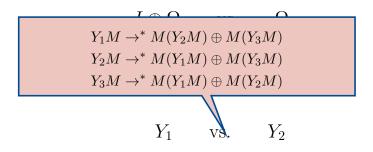
 $(\lambda x.I) \oplus (\lambda x.\Omega)$ vs. $\lambda x.I \oplus \Omega$

$I \oplus \Omega$ vs. I $I \oplus \Omega$ vs. Ω

 $(\lambda x.I) \oplus (\lambda x.\Omega)$ vs. $\lambda x.I \oplus \Omega$

 Y_1 vs. Y_2

$I \oplus \Omega$ vs. I



Terms

Terms

Values

Terms

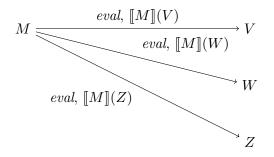
Values

M

Terms

Values

÷



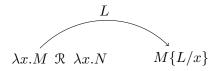
Terms

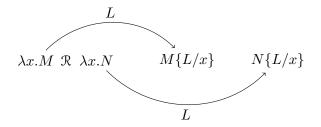
Values

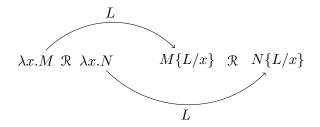
$\lambda x.N$

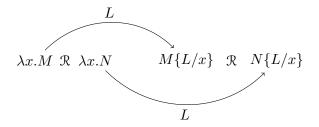


 $\lambda x.M \ \mathcal{R} \ \lambda x.N$

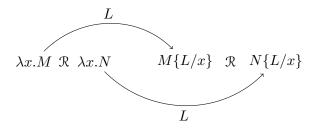


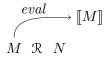


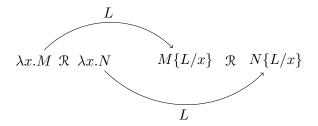


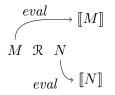


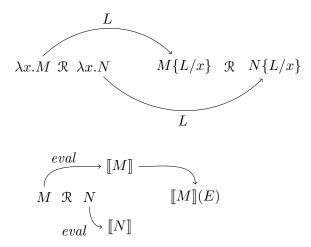
 $M \mathcal{R} N$

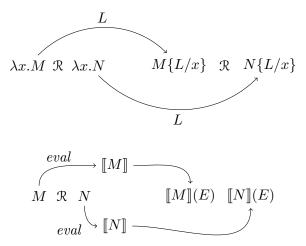


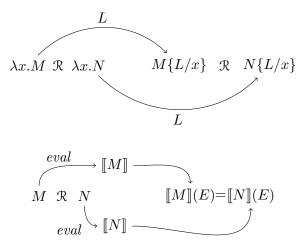












Applicative Bisimilarity vs. Context Equivalence

- **Bisimilarity**: the union \sim of all bisimulation relations.
- Is it that \sim is included in \equiv ? How to prove it?
- ▶ Natural strategy: is \sim a congruence?
 - ▶ If this is the case:

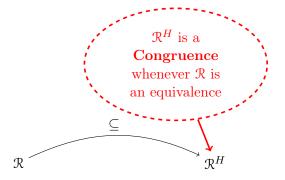
$$\begin{split} M \sim N \implies C[M] \sim C[N] \implies \sum \llbracket C[M] \rrbracket = \sum \llbracket C[N] \rrbracket \\ \implies M \equiv N. \end{split}$$

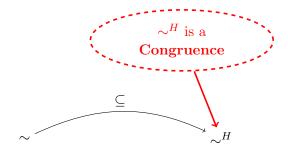
- ▶ This is a necessary sanity check anyway.
- ▶ The naïve proof by induction **fails**, due to application: from $M \sim N$, one cannot directly conclude that $LM \sim LN$.

 \mathcal{R}

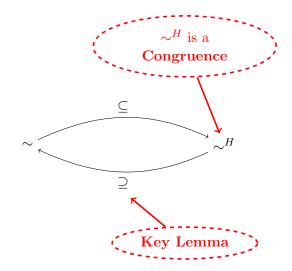
 \mathcal{R}^{H}





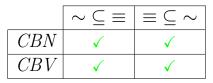


Howe's Technique



Our Neighborhood

• Λ , where we observe **convergence**

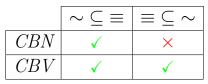


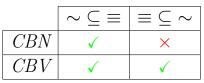
[Abramsky1990, Howe1993]

∧⊕ with nondeterministic semantics, where we observe convergence, in its may or must flavors.

	$\sim \subseteq \equiv$	\equiv \subseteq \sim
CBN	\checkmark	×
CBV	\checkmark	×

[Ong1993, Lassen1998]





- ► Counterexample for CBN: $(\lambda x.I) \oplus (\lambda x.\Omega) \not\sim \lambda x.I \oplus \Omega$
- Where these discrepancies come from?



- ► Counterexample for CBN: $(\lambda x.I) \oplus (\lambda x.\Omega) \not\sim \lambda x.I \oplus \Omega$
- Where these discrepancies come from?
- From testing!

$$\begin{array}{c|c} \sim \subseteq \equiv & \equiv \subseteq \sim \\ \hline CBN & \checkmark & \times \\ \hline CBV & \checkmark & \checkmark \end{array}$$

- ► Counterexample for CBN: $(\lambda x.I) \oplus (\lambda x.\Omega) \not\sim \lambda x.I \oplus \Omega$
- Where these discrepancies come from?
- From testing!
- Bisimulation can be characterized by testing equivalence as follows:

Calculus	Testing			
Λ	$T ::= \omega \mid a \cdot T$			
$P\Lambda_\oplus$	$T ::= \omega \mid a \cdot T \mid \langle T, T \rangle$			
$N\Lambda_\oplus$	$T ::= \omega \mid a \cdot T \mid \wedge_{i \in I} T_i \mid \dots$			



• Λ_{\oplus} with probabilistic semantics.

$$\begin{array}{c|c} \overrightarrow{} \subseteq \leq \leq \subseteq \overrightarrow{} \\ \hline CBN & \checkmark & \times \\ \hline CBV & \checkmark & \times \end{array}$$

 Probabilistic simulation can be characterized by testing as follows:

$$T ::= \omega \mid a \cdot T \mid \langle T, T \rangle \mid T \lor T$$

• Λ_{\oplus} with probabilistic semantics.

$$\begin{array}{c|c} \overrightarrow{} \subseteq \leq \leq \subseteq \overrightarrow{} \\ \hline CBN & \checkmark & \times \\ \hline CBV & \checkmark & \times \end{array}$$

 Probabilistic simulation can be characterized by testing as follows:

$$T ::= \omega \mid a \cdot T \mid \langle T, T \rangle \mid T \lor T$$

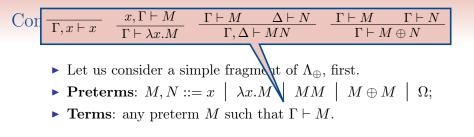
► Full abstraction can be recovered if endowing Λ_{\oplus} with parallel disjunction [CDLSV2015].

	$\precsim \subseteq \leq$	\leq \subseteq \precsim
CBN	\checkmark	×
CBV	\checkmark	\checkmark

• Let us consider a simple fragment of Λ_{\oplus} , first.

- Let us consider a simple fragment of Λ_{\oplus} , first.
- ▶ **Preterms**: $M, N ::= x \mid \lambda x.M \mid MM \mid M \oplus M \mid \Omega;$

- ▶ Let us consider a simple fragment of Λ_{\oplus} , first.
- ▶ **Preterms**: $M, N ::= x \mid \lambda x.M \mid MM \mid M \oplus M \mid \Omega;$
- ▶ **Terms**: any preterm M such that $\Gamma \vdash M$.



- ▶ Let us consider a simple fragment of Λ_{\oplus} , first.
- ▶ **Preterms**: $M, N ::= x \mid \lambda x.M \mid MM \mid M \oplus M \mid \Omega;$
- **Terms**: any preterm M such that $\Gamma \vdash M$.
- Behavioural Distance δ^b .
 - ▶ The metric analogue to bisimilarity.

- Let us consider a simple fragment of Λ_{\oplus} , first.
- ▶ **Preterms**: $M, N ::= x \mid \lambda x.M \mid MM \mid M \oplus M \mid \Omega;$
- **Terms**: any preterm M such that $\Gamma \vdash M$.
- Behavioural Distance δ^b .
 - ▶ The metric analogue to bisimilarity.
- Trace Distance δ^t .
 - ► The maximum distance induced by traces, i.e., sequences of actions: $\delta^t(M, N) = \sup_{\mathsf{T}} |Pr(M, \mathsf{T}) Pr(N, \mathsf{T})|.$

- ▶ Let us consider a simple fragment of Λ_{\oplus} , first.
- ▶ **Preterms**: $M, N ::= x \mid \lambda x.M \mid MM \mid M \oplus M \mid \Omega;$
- **Terms**: any preterm M such that $\Gamma \vdash M$.
- Behavioural Distance δ^b .
 - ▶ The metric analogue to bisimilarity.
- Trace Distance δ^t .
 - ► The maximum distance induced by traces, i.e., sequences of actions: $\delta^t(M, N) = \sup_{\mathsf{T}} |Pr(M, \mathsf{T}) Pr(N, \mathsf{T})|.$
- ▶ Soundness and Completeness Results:

$\delta^b \leq \delta^c$	$\delta^c \leq \delta^b$	$\delta^t \leq \delta^c$	$\delta^c \leq \delta^t$
\checkmark	×	\checkmark	\checkmark

- ▶ Let us consider a simple fragment of Λ_{\oplus} , first.
- ▶ **Preterms**: $M, N ::= x \mid \lambda x.M \mid MM \mid M \oplus M \mid \Omega;$
- **Terms**: any preterm M such that $\Gamma \vdash M$.
- Behavioural Distance δ^b .
 - ▶ The metric analogue to bisimilarity.
- Trace Distance δ^t .
 - ► The maximum distance induced by traces, i.e., sequences of actions: $\delta^t(M, N) = \sup_{\mathsf{T}} |Pr(M, \mathsf{T}) Pr(N, \mathsf{T})|.$
- ▶ Soundness and Completeness Results:

$$\begin{array}{c|c|c|c|c|c|c|c|c|}\hline \delta^b \leq \delta^c & \delta^c \leq \delta^c & \delta^c \leq \delta^t \\ \hline \checkmark & \times & \checkmark & \checkmark & \hline \end{array}$$

• **Example**: $\delta^t(I, I \oplus \Omega) = \delta^t(I \oplus \Omega, \Omega) = \frac{1}{2}$.

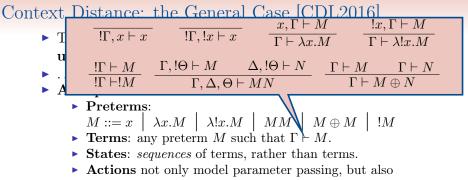
► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...

- ► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...
- ... because it **does not** adequately model copying.

- ► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...
- ... because it **does not** adequately model copying.
- A Tuple LMC.
 - Preterms:

 $M ::= x \mid \lambda x.M \mid \lambda ! x.M \mid MM \mid M \oplus M \mid !M$ • Terms: any preterm M such that $\Gamma \vdash M$.

- ▶ States: sequences of terms, rather than terms.
- Actions not only model parameter passing, but also *copying* of terms.

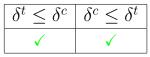


copying of terms.

- ► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...
- ... because it **does not** adequately model copying.
- A Tuple LMC.
 - Preterms:

 $M ::= x \mid \lambda x.M \mid \lambda ! x.M \mid MM \mid M \oplus M \mid !M$ • Terms: any preterm M such that $\Gamma \vdash M$.

- ▶ States: *sequences* of terms, rather than terms.
- Actions not only model parameter passing, but also *copying* of terms.
- Soundness and Completeness Results:



- ► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...
- ... because it **does not** adequately model copying.
- A Tuple LMC.
 - Preterms:

 $M ::= x \mid \lambda x.M \mid \lambda ! x.M \mid MM \mid M \oplus M \mid !M$ • Terms: any preterm M such that $\Gamma \vdash M$.

- ▶ States: *sequences* of terms, rather than terms.
- Actions not only model parameter passing, but also *copying* of terms.
- ▶ Soundness and Completeness Results:

$$\begin{array}{c|c} \delta^t \leq \delta^c & \delta^c \leq \delta^t \\ \hline \checkmark & \checkmark \end{array}$$

► Examples: $\delta^t(!(I \oplus \Omega), !\Omega) = \frac{1}{2} \qquad \delta^t(!(I \oplus \Omega), !I) = 1.$

- ► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...
- ... because it **does not** adequately model copying.
- A Tuple LMC.
 - Preterms:

 $M ::= x \mid \lambda x.M \mid \lambda ! x.M \mid MM \mid M \oplus M \mid !M$ • Terms: any preterm M such that $\Gamma \vdash M$.

- ▶ States: *sequences* of terms, rather than terms.
- Actions not only model parameter passing, but also *copying* of terms.
- ▶ Soundness and Completeness Results:

$$\begin{array}{c|c} \delta^t \leq \delta^c & \delta^c \leq \delta^t \\ \hline \checkmark & \checkmark \end{array}$$

- ► Examples: $\delta^t(!(I \oplus \Omega), !\Omega) = \frac{1}{2}$ $\delta^t(!(I \oplus \Omega), !I) = 1.$
- ▶ **Trivialisation**: the context distance *collapses* to an equivalence in *strongly normalising* fragments or in presence of *parellel disjuction*.

- ► The LMC we have have worked so far with induces **unsound** metrics for Λ_{\oplus} ...
- ... because it **does not** adequately model copying.
- A Tuple LMC.
 - Preterms:

 $M ::= x \mid \lambda x.M \mid \lambda ! x.M \mid MM \mid M \oplus M \mid !M$

- ► **Terms**: any preterm M such that $\Gamma \vdash M$.
- ▶ **States**: *sequences* of terms, rather than terms.
- Actions not only model parameter passing, but also copying of terms.
- Soundness and Comple What would a sensible notion of

distance look like?

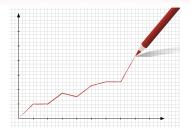
- ► Examples: $\delta^t(!(I \oplus \Omega), !\Omega) = \frac{1}{2} \qquad \delta^t(!(I \oplus \Omega), !I) = 1.$
- ▶ **Trivialisation**: the context distance *collapses* to an equivalence in *strongly normalising* fragments or in presence of *parellel disjuction*.

Part II

Bayesian Functional Programming













2. let
$$x = \text{sample}(bern\left(\frac{5}{7}\right))$$
 in

3. let
$$r = \text{ if } x \text{ then } 10 \text{ else } 3 \text{ in}$$

4. observe 4 from
$$poisson(r)$$
;

5.
$$\operatorname{return}(x)$$

2. let
$$x = \text{sample}(bern\left(\frac{5}{7}\right))$$
 in

3. let
$$r = \text{ if } x \text{ then } 10 \text{ else } 3 \text{ in}$$

4. observe 4 from
$$poisson(r)$$
;

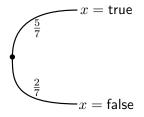
5.
$$\operatorname{return}(x)$$
)

2. let
$$x = \text{sample}(bern\left(\frac{5}{7}\right))$$
 in

3. let
$$r = \text{ if } x \text{ then } 10 \text{ else } 3 \text{ in}$$

4. observe 4 from
$$poisson(r)$$
;

5.
$$\operatorname{return}(x)$$
)

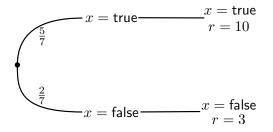


2. let
$$x = \text{sample}(bern\left(\frac{5}{7}\right))$$
 in

3. let r = if x then 10 else 3 in

4. observe 4 from
$$poisson(r)$$
;

5.
$$\operatorname{return}(x)$$

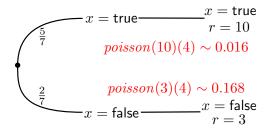


2. let
$$x = \text{sample}(bern\left(\frac{5}{7}\right))$$
 in

3. let
$$r = \text{ if } x \text{ then } 10 \text{ else } 3 \text{ in}$$

4. observe 4 from poisson(r);

5.
$$\operatorname{return}(x)$$

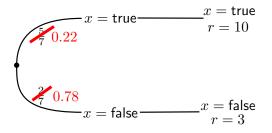


2. let
$$x = \text{sample}(bern\left(\frac{5}{7}\right))$$
 in

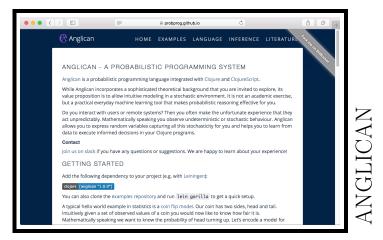
3. let
$$r = \text{ if } x \text{ then } 10 \text{ else } 3 \text{ in}$$

4. observe 4 from
$$poisson(r)$$
;

5. $\operatorname{return}(x)$)



Bayesian Functional Programming



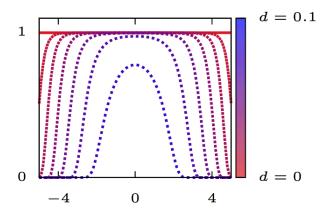
Bayesian Functional Programming

	hakaru-dev.github.io Č Å 🗇 +			
Hakaru Introduction -	Workflow and Examples + Language Guide + Transformations + Internals +			
	Q Search ← Previous Next → O GiltHub			
Quick Start: A Mixture Model Example	Quick Start: A Mixture Model Example			
Modeling a Bernoulli Experiment Creating a Mixture	Let's start with a simple model of a coin toss experiment so that you can become familiar with some of Hakaru's data types and functionality. We will assume that a single coin flip can be represented using a Bernoulli distribution. After we have created the Bernoulli model, we will use it to create a mixture model and condition the model to estimate what the original coin toss experiment looked like based on the resulting mixture model samples.			
Model Conditioning a Hakaru				
Program	Modeling a Bernoulli Experiment			
	We will use the [categorical Hakaru Random Primitive to write a Bernoulli distribution ¹ for our model. The [categorical_primitive requires an array representing the probability of achieving each category in the experiment. Let's start with a fair experiment and state that each side of the coin has an equal chance of being picked. The result of the coin toss is stored in the variable b using Hakaru's notation for bind:			
	<pre>b ~ categorical([0.5, 0.5])</pre>			
	For data type simplicity, we will map Heads to <u>true</u> and Tails to <u>failse</u> . By putting the values of true and <u>failse</u> into an array, we can use the value in <u>b</u> to select which of them to return as the result of the coin toss:			
	b using Hakaru's notation for bind: b <~ categorical((0.5, 0.5)) For data type simplicity, we will map Heads to true and Tails to false. By putting the values of true and false into a rary, we can use the value in b to select which of them to return as the result of the coin toss: return (true, false)(b)			
A characteristic of the Bernoulli distribution is that it assumes that only one experiment is conducted. To collect samples, we need to run this experiment multiple times. To aid in this task				

- 1. normalize(
- 2. let $x = \operatorname{sample}(gauss(0,1))$ in
- 4. observe *d* from exp(1/f(x));
- 5. $\operatorname{return}(x)$)

- 1. normalize(
- 2. let x = sample(gauss(0,1)) in
- 4. observe *d* from exp(1/f(x));

5.
$$\operatorname{return}(x)$$



- Giving semantics to programming languages like Anglican or Hakaru is nontrivial:
 - Real numbers;
 - ► Sampling from **continuous** distributions;
 - Conditioning.

- Giving semantics to programming languages like Anglican or Hakaru is nontrivial:
 - Real numbers;
 - ▶ Sampling from **continuous** distributions;
 - Conditioning.
- Key ingredients:
 - ▶ In $M \Downarrow D$, we need D to be a *measure*, because the set of term is not countable anymore.

- Giving semantics to programming languages like Anglican or Hakaru is nontrivial:
 - Real numbers;
 - ► Sampling from **continuous** distributions;
 - Conditioning.
- Key ingredients:
 - ▶ In $M \Downarrow D$, we need D to be a *measure*, because the set of term is not countable anymore.
 - Terms must thus be equipped with the structure of a measurable space.

- Giving semantics to programming languages like Anglican or Hakaru is nontrivial:
 - Real numbers;
 - ▶ Sampling from **continuous** distributions;
 - Conditioning.

• Key ingredients:

- ▶ In $M \Downarrow D$, we need D to be a *measure*, because the set of term is not countable anymore.
 - Terms must thus be equipped with the structure of a measurable space.

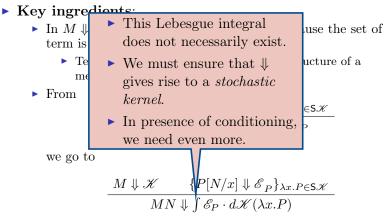
► From

$$\frac{M \Downarrow \mathscr{K} \qquad \{P[N/x] \Downarrow \mathscr{E}_P\}_{\lambda x.P \in \mathsf{S}\mathscr{K}}}{MN \Downarrow \sum_{\lambda x.P \in \mathsf{S}\mathscr{K}} \mathscr{K}(\lambda x.P) \cdot \mathscr{E}_P}$$

we go to

$$\frac{M \Downarrow \mathscr{K} \qquad \{P[N/x] \Downarrow \mathscr{E}_P\}_{\lambda x.P \in \mathsf{S}\mathscr{K}}}{MN \Downarrow \int \mathscr{E}_P \cdot d\mathscr{K}(\lambda x.P)}$$

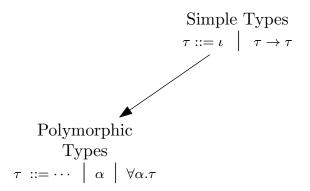
- Giving semantics to programming languages like Anglican or Hakaru is nontrivial:
 - Real numbers;
 - ► Sampling from **continuous** distributions;
 - Conditioning.

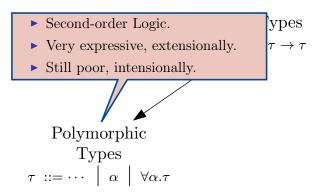


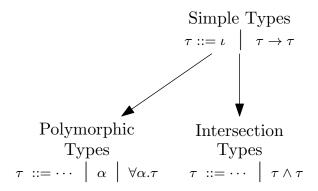
Part III

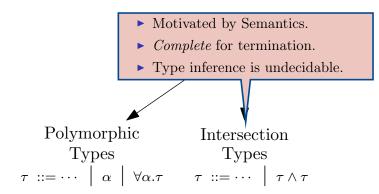
Termination

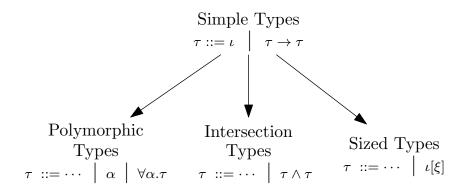
Simple Types
$$\tau ::= \iota \mid \tau \to \tau$$

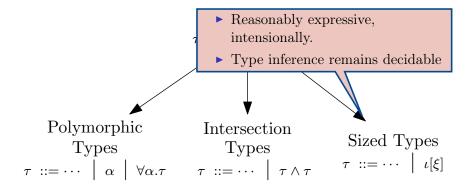








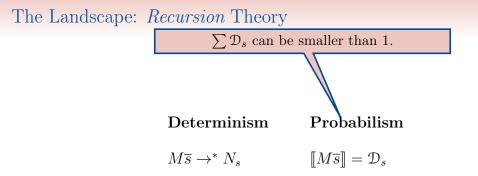


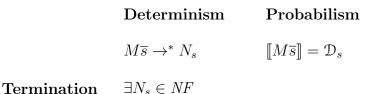


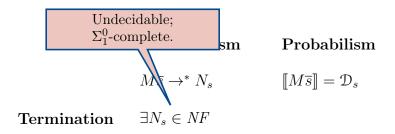
Determinism

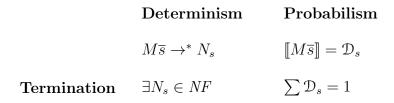
 $M\overline{s} \rightarrow^* N_s$

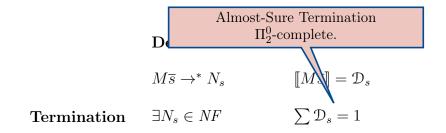
DeterminismProbabilism $M\overline{s} \rightarrow^* N_s$ $\llbracket M\overline{s} \rrbracket = \mathcal{D}_s$

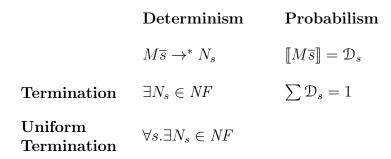


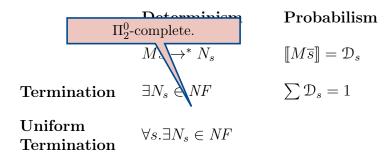




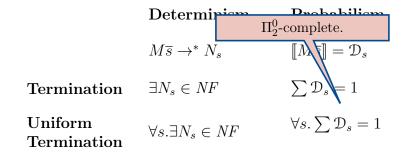








	Determinism	$\mathbf{Probabilism}$
	$M\overline{s} \rightarrow^* N_s$	$\llbracket M\overline{s} \rrbracket = \mathcal{D}_s$
Termination	$\exists N_s \in NF$	$\sum \mathcal{D}_s = 1$
Uniform Termination	$\forall s. \exists N_s \in NF$	$\forall s. \sum \mathcal{D}_s = 1$



- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - But useless as a programming language.

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - But us less as a programming language.
- For every type τ, define a set of reducible terms Red_τ.
- Prove that all reducible terms are normalizing...
- ... and that all typable terms are reducible.

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - ▶ But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?

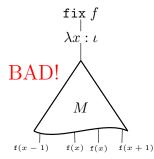
 $(\texttt{fix} x.M)V \to M\{\texttt{fix} x.M/x\}V$

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - ▶ But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?
- ► All the termination properties are **lost**, for very good reasons.

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - ▶ But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?
- ► All the termination properties are **lost**, for very good reasons.
- ► Is everything lost?

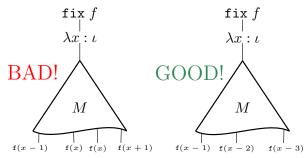
- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - ▶ But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?
- ► All the termination properties are **lost**, for very good reasons.
- ► Is everything lost?
- ▶ NO!

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - ▶ But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?
- ► All the termination properties are **lost**, for very good reasons.
- Is everything lost?
- ▶ NO!



Deterministic Sized Types

- Pure λ -calculus with simple types is terminating.
 - This can be proved in many ways, including by reducibility.
 - ▶ But useless as a programming language.
- ▶ What if we endow it with **full recursion** as a **fix** binder?
- ► All the termination properties are **lost**, for very good reasons.
- ► Is everything lost?
- ▶ NO!



► Types.

$$\xi ::= a \mid \omega \mid \xi + 1; \qquad \quad \tau ::= \iota[\xi] \mid \tau \to \tau.$$

► Types.

► Types.

$$\xi ::= a \mid \omega \mid \xi + 1; \qquad \quad \tau ::= \iota[\xi] \mid \tau \to \tau.$$

• Typing Fixpoints.

$$\frac{\Gamma, x: \iota[a] \to \tau \vdash M: \iota[a+1] \to \tau}{\Gamma \vdash \texttt{fix} \; x.M: \iota[\xi] \to \tau}$$

Types.

$$\xi ::= a \mid \omega \mid \xi + 1; \qquad \quad \tau ::= \iota[\xi] \mid \tau \to \tau.$$

Typing Fixpoints.

$$\frac{\Gamma, x: \iota[a] \to \tau \vdash M: \iota[a+1] \to \tau}{\Gamma \vdash \texttt{fix} \; x.M: \iota[\xi] \to \tau}$$

Quite Powerful.

▶ Can type many forms of structural recursion.

► Types.

$$\xi ::= a \ \left| \begin{array}{c} \omega \end{array} \right| \ \xi + 1; \qquad \quad \tau ::= \iota[\xi] \ \left| \begin{array}{c} \tau \to \tau. \end{array} \right.$$

► Typing Fixpoints.

$$\frac{\Gamma, x: \iota[a] \to \tau \vdash M: \iota[a+1] \to \tau}{\Gamma \vdash \texttt{fix} \; x.M: \iota[\xi] \to \tau}$$

Quite Powerful.

▶ Can type many forms of structural recursion.

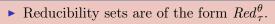
Termination.

- Proved by Reducibility.
- ▶ ... but of an indexed form.

► Types.

$$\xi ::= a \ \left| \begin{array}{c} \omega \end{array} \right| \ \xi + 1; \qquad \quad \tau ::= \iota[\xi] \ \left| \begin{array}{c} \tau \to \tau. \end{array} \right.$$

► Typing Fixpoints.



- \blacktriangleright θ is an environment for index variables.
- ▶ Proof of reducibility for fix x.M is rather delicate.

Termination.

- Proved by Reducibility.
- ... but of an indexed form.

► Types.

$$\xi ::= a \ \left| \begin{array}{c} \omega \end{array} \right| \ \xi + 1; \qquad \quad \tau ::= \iota[\xi] \ \left| \begin{array}{c} \tau \to \tau. \end{array} \right.$$

► Typing Fixpoints.

$$\frac{\Gamma, x: \iota[a] \to \tau \vdash M: \iota[a+1] \to \tau}{\Gamma \vdash \texttt{fix} \; x.M: \iota[\xi] \to \tau}$$

Quite Powerful.

▶ Can type many forms of structural recursion.

Termination.

- Proved by Reducibility.
- ... but of an indexed form.
- ► Type Inference.
 - ▶ It is indeed *decidable*.
 - ▶ But *nontrivial*.

• Examples:

fix $f \cdot \lambda x$.if x > 0 then if *FairCoin* then f(x - 1) else f(x + 1); fix $f \cdot \lambda x$.if x > 0 then if *BiasedCoin* then f(x - 1) else f(x + 1); fix $f \cdot \lambda x$.if *BiasedCoin* then f(x + 1) else x.

• Examples:

fix f. x.if x > 0 then if FairCoin then f(x - 1) else f(x + 1); fix f. x.if x > 0 then if BiasedCoin then f(x - 1) else f(x + 1); Unbiased Random Walk then f(x + 1) else x.

• Examples:

fix $f.\lambda x.$ if x > 0 then if FairCoin then f(x - 1) else f(x + 1); fix f.x. if x > 0 then if BiasedCoin then f(x - 1) else f(x + 1); Unbiased Random Wa

Examples:

fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if FairCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if BiasedCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } BiasedCoin$ then f(x + 1) else x.

Non-Examples:

fix $f \cdot \lambda x$.if FairCoin then f(x-1) else (f(x+1); f(x+1));fix $f \cdot \lambda x$.if BiasedCoin then f(x+1) else f(x-1);

• Examples:

fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if FairCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if BiasedCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } BiasedCoin$ then f(x + 1) else x.

Non-Examples:

fix $f.\lambda x.$ if FairCpin then f(x-1) else (f(x+1); f(x+1));fix $f.\lambda x.$ if Biase Coin then f(x+1) else f(x-1);Unbiased Random Walk, with **two** upward calls.

• Examples:

fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if FairCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if BiasedCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } BiasedCoin$ then f(x + 1) else x.

Non-Examples:

fix $f.\lambda x.$ if FairCoin then f(x-1) else (f(x+1); f(x+1));fix $f.\lambda x.$ if Biase Coin then f(x+1) else f(x-1);Unbiased Random Walk, with two upward calls. Biased Random Walk, the "wrong" way.

Examples:

fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if FairCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } x > 0$ then if BiasedCoin then f(x - 1) else f(x + 1); fix $f \cdot \lambda x \cdot \text{if } BiasedCoin$ then f(x + 1) else x.

Non-Examples:

fix $f \cdot \lambda x$.if FairCoin then f(x-1) else (f(x+1); f(x+1));fix $f \cdot \lambda x$.if BiasedCoin then f(x+1) else f(x-1);

Probabilistic termination is thus:

- ▶ Sensitive to *the actual distribution* from which we sample.
- ▶ Sensitive to how many recursive calls we perform.

One-Counter Blind Markov Chains

▶ They are automata of the form (Q, δ) where

- Q is a finite set of *states*.
- $\blacktriangleright \ \delta: Q \to \mathsf{Dist}(Q \times \{-1,0,1\}).$
- ▶ They are a very special form of One-Counter Markov Decision Processesses [BBEK2011].
 - The model is fully probabilistic, there is no nondeterminism.
 - ▶ The counter value is ignored.

One-Counter Blind Markov Chains

▶ They are automata of the form (Q, δ) where

- Q is a finite set of *states*.
- $\blacktriangleright \ \delta: Q \to \mathsf{Dist}(Q \times \{-1, 0, 1\}).$
- They are a very special form of One-Counter Markov Decision Processesses [BBEK2011].
 - The model is fully probabilistic, there is no nondeterminism.
 - ▶ The counter value is ignored.
- The probability of reaching a configuration where the counter is 0 can be approximated arbitrarily well *in polynomial time*.

▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- ► Judgments.

 $\Gamma \mid \Delta \vdash M : \mu$

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- ► Judgments.

$$\label{eq:Lagrangian} \Gamma \begin{tabular}{|c|c|c|c|} \Delta \vdash M : \mu \\ \end{tabular}$$
 Every higher-order variable occurs **at most once**.

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- Judgments.

 $\Gamma \mid \Delta \vdash M : \mu$

• Typing Fixpoints.

$$\frac{\Gamma \mid x: \sigma \vdash V: \iota[a+1] \rightarrow \tau \quad OCBMC(\sigma) \text{ terminates.}}{\Gamma \mid x: \sigma \vdash V: \iota[\xi] \rightarrow \tau}$$

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- Judgments.

 $\Gamma \mid \Delta \vdash M : \mu$

Typing Fixpoints.

$$\frac{\Gamma \mid x : \sigma \vdash V : \iota[a+1] \rightarrow \tau \quad OCBMC(\sigma) \text{ terminates}}{\Gamma \mid x : \sigma} \quad V : \iota[\xi] \rightarrow \tau$$
This is sufficient for typing:

Unbiased random walks;
Biased random walks.

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- Judgments.

 $\Gamma \mid \Delta \vdash M : \mu$

Typing Fixpoints.

$$\frac{\Gamma \mid x: \sigma \vdash V: \iota[a+1] \rightarrow \tau \quad OCBMC(\sigma) \text{ terminates.}}{\Gamma \mid x: \sigma \vdash V: \iota[\xi] \rightarrow \tau}$$

Typing Probabilistic Choice

$$\frac{\Gamma \mid \Delta \vdash M : \tau \quad \Gamma \mid \Omega \vdash N : \rho}{\Gamma \mid \frac{1}{2}\Delta + \frac{1}{2}\Omega \vdash M \oplus N : \frac{1}{2}\tau + \frac{1}{2}\rho}$$

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- Judgments.

 $\Gamma \mid \Delta \vdash M : \mu$

Typing Fixpoints.

$$\frac{\Gamma \mid x: \sigma \vdash V: \iota[a+1] \rightarrow \tau \quad OCBMC(\sigma) \text{ terminates.}}{\Gamma \mid x: \sigma \vdash V: \iota[\xi] \rightarrow \tau}$$

Typing Probabilistic Choice

$$\frac{\Gamma \mid \Delta \vdash M: \tau \quad \Gamma \mid \Omega \vdash N: \rho}{\Gamma \mid \frac{1}{2}\Delta + \frac{1}{2}\Omega \vdash M \oplus N: \frac{1}{2}\tau + \frac{1}{2}\rho}$$

▶ Termination.

▶ By a quantitative nontrivial refinement of reducibility.

- ▶ **Basic Idea**: craft a sized-type system in such a way as to mimick the recursive structure by a OCBMC.
- Judgments.

 $\Gamma \mid \Delta \vdash M : \mu$

ates.

Typing Fixpoints.

- Reducibility sets are now on the form $Red_{\tau}^{\theta,p}$
- p stands for the *probability* of being reducible.
- Reducibility sets are continuous:

$$Red_{\tau}^{\theta,p} = \bigcup_{q < p} Red_{\tau}^{\theta,q}$$

- ► Termination.
 - ▶ By a quantitative nontrivial refinement of reducibility.

• **Question**: what are simple types *missing* as a way to precisely capture *termination*?

- **Question**: what are simple types *missing* as a way to precisely capture *termination*?
- Very simple examples of normalizing terms which *canoot* be typed:

$$\Delta = \lambda x.xx \qquad \quad \Delta(\lambda x.x).$$

- **Question**: what are simple types *missing* as a way to precisely capture *termination*?
- Very simple examples of normalizing terms which *canoot* be typed:

$$\Delta = \lambda x. xx \qquad \quad \Delta(\lambda x. x).$$



$$\tau ::= \star | A \to B \qquad A ::= \{\tau_1, \dots, \tau_n\}$$

- **Question**: what are simple types *missing* as a way to precisely capture *termination*?
- Very simple examples of normalizing terms which *canoot* be typed:

$$\Delta = \lambda x.xx \qquad \quad \Delta(\lambda x.x).$$

Types

$$\tau ::= \star \mid A \to B \qquad A ::= \{\tau_1, \dots, \tau_n\}$$

$$\frac{\{\Gamma \vdash M : \tau_i\}_{1 \le i \le n}}{\Gamma \vdash M : \{\tau_1, \dots, \tau_n\}} \qquad \qquad \frac{\Gamma \vdash M : \{A \to B\} \quad \Gamma \vdash N : A}{\Gamma \vdash MN : B}$$

- **Question**: what are simple types *missing* as a way to precisely capture *termination*?
- Very simple examples of normalizing terms which *canoot* be typed:

$$\Delta = \lambda x.xx \qquad \quad \Delta(\lambda x.x).$$

Types

$$\tau ::= \star \mid A \to B \qquad A ::= \{\tau_1, \dots, \tau_n\}$$

► Typing Rules: Examples $\frac{\{\Gamma \vdash M : \tau_i\}_{1 \le i \le n}}{\Gamma \vdash M : \{\tau_1, \dots, \tau_n\}} \qquad \frac{\Gamma \vdash M : \{A \to B\} \quad \Gamma \vdash N : A}{\Gamma \vdash MN : B}$

Termination

• Again by reducibility.

- **Question**: what are simple types *missing* as a way to precisely capture *termination*?
- Very simple examples of normalizing terms which *canoot* be typed:

$$\Delta = \lambda x.xx \qquad \quad \Delta(\lambda x.x).$$

Types

$$\tau ::= \star \mid A \to B \qquad A ::= \{\tau_1, \dots, \tau_n\}$$

► Typing Rules: Examples

 $\frac{\{\Gamma \vdash M : \tau_i\}_{1 \le i \le n}}{\Gamma \vdash M : \{\tau_1, \dots, \tau_n\}} \qquad \qquad \frac{\Gamma \vdash M : \{A \to B\} \quad \Gamma \vdash N : A}{\Gamma \vdash MN : B}$

Termination

- Again by reducibility.
- Completeness
 - ▶ By *subject expansion*, the dual of subject reduction.

▶ Probabilistic choice can be seen as a form of read operation:

 $M \oplus N = \operatorname{if} BitInput \operatorname{then} M \operatorname{else} N$

▶ Probabilistic choice can be seen as a form of read operation:

 $M \oplus N = \operatorname{if} BitInput \operatorname{then} M \operatorname{else} N$

Types

$$\tau ::= \star | A \to s \cdot B \qquad A ::= \{\tau_1, \dots, \tau_n\} \qquad s \in \{0, 1\}^*$$

▶ Probabilistic choice can be seen as a form of read operation:

 $M \oplus N = \operatorname{if} BitInput \operatorname{then} M \operatorname{else} N$

Types

$$\tau ::= \star | A \to s \cdot B \qquad A ::= \{\tau_1, \dots, \tau_n\} \qquad s \in \{0, 1\}^*$$

► Typing Rules: Examples

$$\frac{\Gamma \vdash M: s \cdot A}{\Gamma \vdash M \oplus N: 0s \cdot A} \qquad \frac{\Gamma \vdash M: r \cdot \{A \to s \cdot B\} \quad \Gamma \vdash N: q \cdot A}{\Gamma \vdash MN: (rqs) \cdot B}$$

▶ Probabilistic choice can be seen as a form of read operation:

 $M \oplus N = \texttt{if} \; BitInput \; \texttt{then} \; M \; \texttt{else} \; N$

$$\tau ::= \star | A \to s \cdot B \qquad A ::= \{\tau_1, \dots, \tau_n\} \qquad s \in \{0, 1\}^*$$

► Typing Rules: Examples

$$\frac{\Gamma \vdash M : s \cdot A}{\Gamma \vdash M \oplus N : 0s \cdot A} \qquad \frac{\Gamma \vdash M : r \cdot \{A \to s \cdot B\}}{\Gamma \vdash MN : (rqs) \cdot B}$$

Termination and Completeness

- ▶ Formulated in a rather *unusual* way.
- Proved as usual, but relative to a single probabilistic branch

▶ Probabilistic choice can be seen as a form of read operation:

 $M \oplus N = \operatorname{if} BitInput \operatorname{then} M \operatorname{else} N$

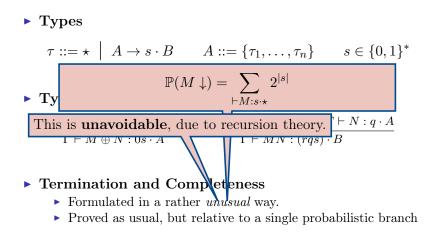
Types
τ ::= ★ | A → s ⋅ B A ::= {τ₁,...,τ_n} s ∈ {0,1}*
Ty
P(M ↓) = ∑_{⊢M:s ⋅ ⋆} 2^{|s|}
Ty
Γ⊢M:s ⋅ A Γ⊢M Γ⊢N:q ⋅ A

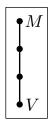
Termination and Completeness

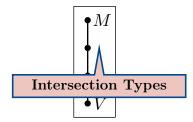
- ▶ Formulated in a rather *unusual* way.
- Proved as usual, but relative to a single probabilistic branch

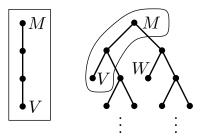
▶ Probabilistic choice can be seen as a form of read operation:

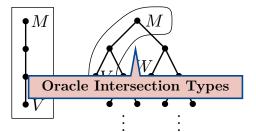
 $M \oplus N = \operatorname{if} BitInput \operatorname{then} M \operatorname{else} N$

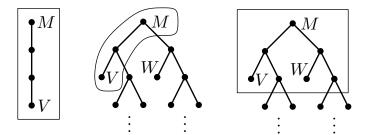






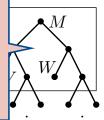






Monadic Intersection Types [BDL2017]

- They are a combination of oracle and sized types.
- ▶ Intersections are needed for preciseness.
- Distributions of types allow to analyse more than one probabilistic branch in the same type derivation.



These Slides, and More...



These Slides, and More...



Questions?