

1-Laplacian on metric random walk spaces

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Abstract

We study the nonlocal 1-Laplacian operator in a quite general framework of metric random walk spaces. These include as special cases locally finite graphs and Euclidean spaces with nonlocality given by a nonnegative radial kernel. We provide some geometric conditions on the space and the random walk under which the problem admits a solution and study its properties. This poster is based on a joint work with Jose M. Mazón.

Introduction

The starting point of this presentation is the least gradient problem ([1, 6])

$$\min \left\{ \int_{\Omega} |Du| : u \in BV(\Omega), u|_{\partial\Omega} = h \right\}. \quad (1)$$

Depending on the regularity of h and geometry of Ω , the boundary condition can be understood in several different ways. The approach we will focus is the relaxed formulation: assume that Ω is an open bounded set, $\partial\Omega$ is Lipschitz and $h \in L^1(\partial\Omega)$. The relaxed energy functional associated to problem (1) is the functional $\Phi_h : L^{\frac{N}{N-1}}(\Omega) \rightarrow (-\infty, +\infty]$:

$$\Phi_h(u) = \begin{cases} \int_{\Omega} |Du| + \int_{\partial\Omega} |u - h| d\mathcal{H}^{N-1} & \text{if } u \in BV(\Omega), \\ +\infty & \text{if } u \in L^{\frac{N}{N-1}}(\Omega) \setminus BV(\Omega). \end{cases} \quad (2)$$

The Euler-Lagrange equation corresponding to minimisation of Φ_h is the Dirichlet problem for the 1-Laplacian operator (see [4])

$$\begin{cases} -\operatorname{div} \left(\frac{Du}{|Du|} \right) = 0, & \text{in } \Omega, \\ u = h, & \text{on } \partial\Omega. \end{cases} \quad (3)$$

It admits a solution $u \in BV(\Omega)$ for every $h \in L^1(\partial\Omega)$. Moreover, all the solutions can be characterised using a single vector field $\mathbf{z} \in L^{\infty}(\Omega; \mathbb{R}^N)$.

Here, we present a nonlocal counterpart of the above results developed in [2] together with Jose M. Mazón. This is done in a unified framework of metric random walk spaces, which include as special cases the nonlocality defined via a symmetric nonnegative kernel on \mathbb{R}^N , ε -step random walks on Ahlfors regular spaces, and the case of locally finite weighted graphs. We study a nonlocal counterpart of the 1-Laplacian and give a characterisation of solutions to the Dirichlet problem.

Metric random walk spaces

A metric random walk space (X, d, m) is a Polish metric space (X, d) equipped with a random walk m , i.e. a family of probability measures m_x (for $x \in X$) with finite first moment such that the measures m_x depend in a Borel measurable way on the point $x \in X$.

A Radon measure ν on X is invariant for the random walk m if for any $u \in L^1(X, \nu)$

$$\int_X u(x) d\nu(x) = \int_X \left(\int_X u(y) dm_x(y) \right) d\nu(x).$$

The measure ν is said to be reversible if a more detailed balance condition holds:

$$dm_x(y) d\nu(x) = dm_y(x) d\nu(y).$$

Examples of invariant and reversible random walks include \mathbb{R}^N equipped with a radially symmetric kernel $J : \mathbb{R}^N \rightarrow [0, \infty)$ and locally finite weighted graphs.

We also define the space $BV_m(X)$ associated to the random walk $m = (m_x)$

$$BV_m(X) := \left\{ u : X \rightarrow \mathbb{R} \text{ } \nu\text{-measurable} : \frac{1}{2} \int_X \int_X |u(y) - u(x)| dm_x(y) d\nu(x) < \infty \right\}.$$

We have $L^1(X, \nu) \subset BV_m(X)$. The quantity on the right is called the m -total variation and is denoted by $TV_m(u)$. It is convex, continuous with respect to convergence in $L^1(X, \nu)$ and lower semicontinuous with respect to weak convergence in $L^1(X, \nu)$.

Notions of solutions

Formulation of the Dirichlet problem for the m -total variation faces an additional difficulty which does not appear in the Euclidean case. Since the range of interaction is positive, the boundary datum ψ needs to be defined on a set larger than the topological boundary of Ω . Given $\Omega \subset X$ a ν -measurable set, we define its m -boundary as

$$\partial_m \Omega := \{x \in X \setminus \Omega : m_x(\Omega) > 0\}.$$

We set $\Omega_m := \Omega \cup \partial_m \Omega$. For $\psi \in L^1(\partial_m \Omega, \nu)$ and $u \in BV_m(\Omega)$, we define the function

$$u_{\psi}(x) := \begin{cases} u(x) & \text{if } x \in \Omega \\ \psi(x) & \text{if } x \in \partial_m \Omega. \end{cases}$$

Consider the relaxed energy functional $\mathcal{J}_{\psi} : L^1(\Omega, \nu) \rightarrow [0, +\infty]$ given by

$$\mathcal{J}_{\psi}(u) := TV_m(u_{\psi}) = \frac{1}{2} \int_{\Omega_m} \int_{\Omega_m} |u_{\psi}(y) - u_{\psi}(x)| dm_x(y) d\nu(x). \quad (4)$$

For arbitrary $\psi \in L^{\infty}(\partial_m \Omega, \nu)$ we easily prove existence of minimisers of \mathcal{J}_{ψ} using lower semicontinuity of the m -total variation with respect to weak convergence in $L^1(X, \nu)$.

Our goal is to provide an Euler-Lagrange characterisation of minimisers of \mathcal{J}_{ψ} . This is done using the m -1-Laplacian operator Δ_1^m , first introduced in [5] and formally defined as

$$\Delta_1^m u(x) = \int_{\Omega_m} \frac{u_{\psi}(y) - u(x)}{|u_{\psi}(y) - u(x)|} dm_x(y) \quad \text{for } x \in \Omega.$$

Now, we are ready to introduce a notion of solutions to the nonlocal 1-Laplace problem with Dirichlet boundary condition ψ

$$\begin{cases} -\Delta_1^m u(x) = 0, & x \in \Omega, \\ u(x) = \psi(x), & x \in \partial_m \Omega. \end{cases} \quad (5)$$

Definition 1. Let $\psi \in L^1(\partial_m \Omega, \nu)$. We say that $u \in BV_m(\Omega)$ is a solution to (5) if there exists $g \in L^{\infty}(\Omega_m \times \Omega_m, \nu \otimes \nu)$ with $\|g\|_{\infty} \leq 1$ verifying

$$g(x, y) = -g(y, x) \quad \text{for } (\nu \otimes dm_x)\text{-a.e. } (x, y) \text{ in } \Omega_m \times \Omega_m, \quad (6)$$

$$g(x, y) \in \operatorname{sign}(u_{\psi}(y) - u_{\psi}(x)) \quad \text{for } (\nu \otimes dm_x)\text{-a.e. } (x, y) \text{ in } \Omega_m \times \Omega_m, \quad (7)$$

and

$$-\int_{\Omega_m} g(x, y) dm_x(y) = 0 \quad \text{for } \nu\text{-a.e. } x \in \Omega. \quad (8)$$

Existence of solutions

We start by formulating a key geometric assumption required for existence of solutions in the sense of Definition 1.

Definition 2. Let $p \geq 1$. We say that Ω satisfies a nonlocal p -Poincaré Inequality if there exists $\lambda > 0$ such that

$$\lambda \int_{\Omega} |u(x)|^p d\nu(x) \leq \int_{\Omega} \int_{\Omega_m} |u_{\psi}(y) - u(x)|^p dm_x(y) d\nu(x) + \int_{\partial_m \Omega} |\psi(y)|^p d\nu(y)$$

for all $u \in L^p(\Omega, \nu)$ and $\psi \in L^p(\partial_m \Omega, \nu)$.

The nonlocal Poincaré inequality may be viewed as a result that describes how the metric random walk m_x and the topology of X are related. Roughly speaking, its validity means that the probability measures m_x are uniformly distributed around x (or equivalently that the measures m_x do not distinguish between directions). The nonlocal Poincaré inequality holds for a variety of settings, including radial kernels on Euclidean spaces, finite graphs, and ε -step random walks on Ahlfors regular spaces.

The nonlocal Poincaré inequality is a crucial tool in the proof of existence of solutions to (5), because they are obtained using p -Laplace type approximation. Moreover, without this assumptions existence of solutions may fail; there is a counterexample which is a locally finite weighted graph.

Theorem 1. Suppose that $\psi \in L^{\infty}(\partial_m \Omega, \nu)$. If Ω satisfies a nonlocal p -Poincaré inequality for all $p > 1$, then there exists a solution to problem (5).

Once we know that a solution exists, we can use the antisymmetric function g given by Definition 1 to prove a characterisation of minimisers of the functional \mathcal{J}_{ψ} .

Theorem 2. Let $\psi \in L^{\infty}(\partial_m \Omega, \nu)$. If Ω satisfies a nonlocal p -Poincaré inequality for all $p > 1$, then $u \in L^1(\Omega)$ is a minimiser of the functional \mathcal{J}_{ψ} given by the formula (4) if and only if it is a solution to problem (5).

Moreover, as a corollary of the proof we get that all the solutions to these problems can be characterised using a single function g .

Median value property

Given a ν -measurable function $u : \Omega \rightarrow \mathbb{R}$, we decompose the space X as

$$E_+^x = \{y \in X : u_{\psi}(y) > u_{\psi}(x)\}, \quad E_-^x = \{y \in X : u_{\psi}(y) < u_{\psi}(x)\}, \\ E_0^x = \{y \in X : u_{\psi}(y) = u_{\psi}(x)\}.$$

Definition 3. We say that a ν -measurable function $u : \Omega \rightarrow \mathbb{R}$ satisfies the m -median value property if the condition

$$m_x(E_+^x \cup E_0^x) \geq \frac{1}{2} \quad \text{and} \quad m_x(E_-^x \cup E_0^x) \geq \frac{1}{2}. \quad (9)$$

is satisfied for ν -a.e. $x \in \Omega$.

It turns out that solutions to (5) satisfy the nonlocal median value property. In the other direction, it is not necessarily the case; examples to the contrary exist even in Euclidean spaces (see [3]). Nonetheless, a partial converse still holds.

Theorem 3. Suppose that $u \in BV_m(\Omega)$ is a solution to (5). Then it satisfies the m -median value property. Moreover, if $u \in BV_m(\Omega)$ satisfies the m -median value property, then it satisfies Definition 1 except for antisymmetry of the function g .

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